

# Orthogonality in the Hyperbolic Plane

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## 1 INTRODUCTION

Constructions which involve the orthogonality are necessary for the resolution of many problems of the plane hyperbolic geometry, such as the construction of the circumference, the horocycles, the hypercycles[4], translations according to a line, Saccheri[6] and Lambert[5] quadrilaterals and others, in the two models of Poincaré for the hyperbolic plane: the half-plane  $\mathbb{H}^2$  and the unit disc  $\mathbb{D}^2$ [3].

These constructions can be classified in three types[2]:

- 1.- Determination of the orthogonal line to another one given through a point of it.
- 2.- Determination of the unique orthogonal line to a pair of ultraparallel lines.
- 3.- Determination of the orthogonal line to another one given through an outer point.

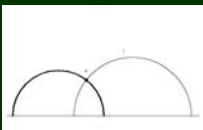
## 2 ORTHOGONAL LINE TO ANOTHER ONE GIVEN THROUGH A POINT OF IT

Given a line  $\Pi$  determine the orthogonal line to  $\Pi$  through a point  $\theta$  belonging to  $\Pi$ .

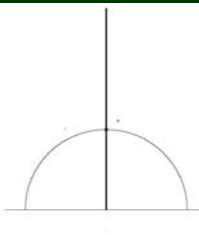
### 2.1 DETERMINATION IN $\mathbb{H}^2$

Let  $\theta$  be the angle determined by the tangent euclidean line to  $\Pi$  at the point  $\theta$  with the euclidean line  $\Xi \neq \emptyset$ . We can consider two cases.

1.-  $\theta \neq 0$



2.-  $\theta = 0$



### 2.2 DETERMINATION IN $\mathbb{D}^2$

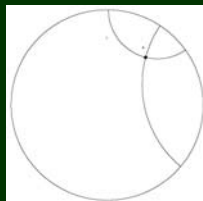
Let  $\theta$  be as point in  $\Pi$ . By the Cayley transformation  $\chi_\Pi$  we construct the line  $\Xi = \chi_\Pi^{-1}(\Pi)$  and the point  $\theta = \chi_\Pi^{-1}(\theta)$  in  $\mathbb{P}^2$ .

Now, in  $\mathbb{P}^2$ , we construct the orthogonal line to  $\Xi$  through  $\theta$ . Applying  $\chi_\Pi$  we obtain the corresponding orthogonal line in  $\mathbb{H}^2$ .

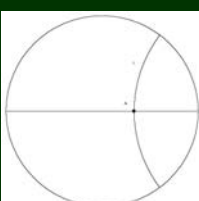
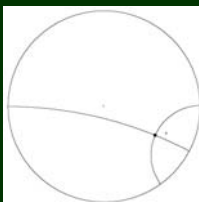
Let  $\theta$  be the angle determined by the euclidean tangent line to  $\Xi$  at the point  $\theta$  with the euclidean line  $\Xi \neq \emptyset$ .

We can consider two cases:

1.-  $\theta \neq 0$



2.-  $\theta = 0$

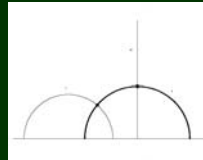
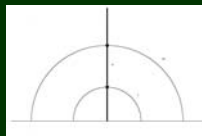


## 3 ORTHOGONAL LINE TO A PAIR OF ULTRAPARALLEL LINES

Given two ultraparallel lines  $\Pi$  and  $\Omega$ , determine the unique orthogonal line to both.

### 3.1 DETERMINATION IN $\mathbb{H}^2$

From the euclidean point of view exist four possibilities of relative position for these two ultraparallel lines. From this, we can obtain the following situations:

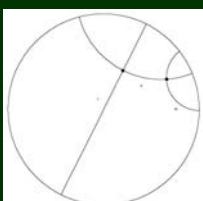
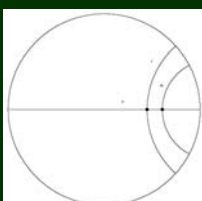
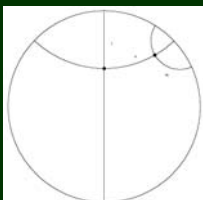
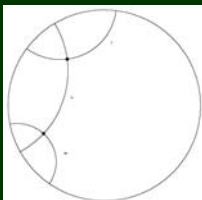


### 3.2 DETERMINATION IN $\mathbb{D}^2$

Let  $\Pi$  and  $\Omega$  two ultraparallel lines in  $\mathbb{H}^2$ . By the Cayley transformation  $\chi_\Pi$  we construct the lines  $\Xi = \chi_\Pi^{-1}(\Pi)$  and  $\Theta = \chi_\Pi^{-1}(\Omega)$  in  $\mathbb{P}^2$ .

Now, in  $\mathbb{P}^2$ , we construct the unique orthogonal line to  $\Xi$  and  $\Theta$ . Applying  $\chi_\Pi$  we obtain the corresponding orthogonal line in  $\mathbb{H}^2$ .

We can obtain the following situations:

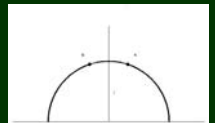


## 4 ORTHOGONAL LINE TO ANOTHER ONE GIVEN THROUGH AN OUTER POINT

Given a line  $\Pi$  and an outer point of it  $\theta$ , determine the orthogonal line to  $\Pi$  through  $\theta$ .

### 3.1 DETERMINATION IN $\mathbb{H}^2$

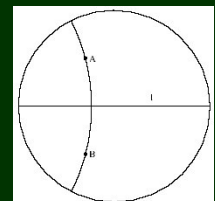
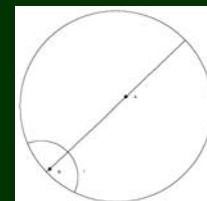
Let  $\theta$  be the reflection of the point  $\theta$  respect to the line  $\Pi$ . The sought orthogonal line is the line through  $\theta$  and  $\theta$ .



### 3.2 DETERMINATION IN $\mathbb{D}^2$

Let  $\Pi$  and  $\theta$  a line and an outer point in  $\mathbb{H}^2$  respectively. By the Cayley transformation  $\chi_\Pi$  we construct the line  $\Xi = \chi_\Pi^{-1}(\Pi)$  and  $\theta = \chi_\Pi^{-1}(\theta)$  in  $\mathbb{P}^2$ .

Now, in  $\mathbb{P}^2$ , we construct the orthogonal line to  $\Xi$  through  $\theta$ . Applying  $\chi_\Pi$  we obtain the corresponding orthogonal line in  $\mathbb{H}^2$ .



## REMARK

We refer the reader to [3], which presents an electronic tool named Hyperbol<sup>(1)</sup> whose computational support is Mathematica software. This tool consists of modules that allow us to draw different hyperbolic constructions in Poincaré's models for the hyperbolic plane, usually denoted by  $\mathbb{H}^2$  and  $\mathbb{D}^2$ . Such constructions include reflections, rotations, translations, glide reflections, and the orbits of a point. These isometries and geometric loci act on the hyperbolic plane; and if a euclidean element appears in some representation of this plane, we shall note it in an explicit way.

<sup>1</sup>Software available at <http://www.ugr.es/local/ruiz/software.htm>

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