# On the Monge-Ampère type equations arising in optimal transport 

Cristian E. Gutiérrez

Temple University, Philadelphia, PA

Dedicated to Ireneo Peral in his 60th birthday
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## INTRODUCTION

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- A cost function is given:
$c(x, y)=$ cost of transporting a unit from $x \in \Omega_{1}$ to $y \in \Omega_{2}$
- Find a measure preserving map $t: \Omega_{1} \rightarrow \Omega_{2}$, i.e., $\left|t^{-1}(E)\right|=|E|$ for each $E \subset \Omega_{2}$ such that minimizes the total cost

$$
\int_{\Omega_{1}} c(x, t(x)) d x
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- Is this problem related to some pde?
- How regular is the optimal map?


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- Kantorovitch (1942) reformulated the problem in probabilistic terms, optimal maps $\rightarrow$ optimal plans, can use linear programming. Formulation weaker than Monge.
$X, Y$ compact metric spaces, $\mu, \nu$ Borel measures on $X$ and $Y$ respectively with $\mu(X)=\nu(Y)$.

Let $\Sigma$ be the class of Borel measures $\sigma$ on $X \times Y$ such that $\sigma(E \times Y)=\mu(E) \forall$ Borel sets $E \subset X$ and $\sigma\left(X \times E^{\prime}\right)=\nu\left(E^{\prime}\right) \forall$ Borel sets $E^{\prime} \subset Y$.

Consider

$$
W(\sigma, \mu, \nu)=\iint_{X \times Y} c(x, y) d \sigma(x, y)
$$

Kantorovitch's formulation is to find a measure $\sigma_{0}$ such that

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W\left(\sigma_{0}, \mu, \nu\right)=\inf _{\sigma \in \Sigma} W(\sigma, \mu, \nu)
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- Kantorovitch, "The best use of economic resources". Methods to solve technical and economic problems such us:
- the least wasteful allocation of work to machines,
- the cutting of material with minimum loss,
- the distributions of loads over several means of transport.
- Impressive number of applications and connections: Calculus of Variations, nonlinear pdes, Convex analysis, Probability, Economics, Statistical Mechanics, and other fields, see book by Rachev and Rüschendorf, Mass transportation problems, two volumes.
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- Kantorovitch and Koopmans received the Nobel prize in Economics in 1975, for "contributions to the theory of optimal allocation of resources".


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- This connects optimal transportation with the Monge-Ampère equation: using his regularity theory for the $M-A$ equation, Caffarelli obtained regularity of the optimal maps.
- For general cost functions we have the following result of Caffarelli, Gangbo and McCann (1996):

Theorem. $\quad c: \mathbb{R}^{n} \rightarrow \mathbb{R}$ strictly convex, $f, g \in L^{1}\left(\mathbb{R}^{n}\right)$ nonnegative with bounded support, and $\int_{\mathbb{R}^{n}} f(x) d x=\int_{\mathbb{R}^{n}} g(y) d y$.

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1. $\exists$ unique $t \in \mathcal{S}(f, g)$ 1-to-1 such that $\mathcal{C}(t)=\inf _{s \in \mathcal{S}(f, g)} \mathcal{C}(s)$;

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1. $\exists$ unique $t \in \mathcal{S}(f, g)$ 1-to-1 such that $\mathcal{C}(t)=\inf _{s \in \mathcal{S}(f, g)} \mathcal{C}(s)$;
2. $\exists$ a c-convex function $u$ such that

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t(x)=x-(D c)^{-1}(-D u(x)) \text { a.e. }
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\partial u(y) & =\left\{p \in \mathbb{R}^{n}: u(x) \geq u(y)+p \cdot(x-y), \forall x \in \Omega\right\} \\
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- Dirichlet problem: if $\Omega$ is strictly convex, $\nu(\Omega)<\infty, g \in C(\partial \Omega)$, then $\exists!u \in C(\bar{\Omega})$ weak solution to

$$
\begin{aligned}
M u & =\nu \\
u & =g \quad \text { on } \partial \Omega .
\end{aligned}
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III

## c-CONVEXITY

- $u: \Omega \rightarrow \mathbb{R} \cup\{+\infty\}$, not identically $+\infty$, is $c$-convex in $\Omega$ if there exists a set $A \subset \mathbb{R}^{n} \times \mathbb{R}$ such that

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u(x)=\sup _{(y, \lambda) \in A}[-c(x-y)-\lambda] \text { for all } x \in \Omega
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- $u$ convex $\Longrightarrow u$ is $c$-convex.


## $c$-SUBDIFFERENTIAL

- Let $u: \Omega \rightarrow \mathbb{R} \cup\{+\infty\}$. The $c$-subdifferential $\partial_{c} u(x)$ at $x \in \Omega$ is defined by

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- If $c(x)=\frac{1}{2}|x|^{2}$, then $p \in \partial_{c} u(x)$ if and only if $p \in \partial(u+c)(x)$, i.e., $\partial_{c} u(x)=\partial(u+c)(x)$ where $\partial$ denotes the standard subdifferential.


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- If $c \in C^{1}\left(\mathbb{R}^{n}\right)$ and strictly convex, and $u$ is differentiable at $x_{0}$, then

$$
\partial_{c} u\left(x_{0}\right)=\left\{x_{0}-(D c)^{-1}\left(-D u\left(x_{0}\right)\right)\right\} .
$$

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where $c^{*}$ is the Legendre-Fenchel transform of $c$

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The notions of $c$-subdifferential and $c$-convexity were introduced by Elster and Nehse (1974) and Dietrich (1988), and recently used by Gangbo and McCann.

IV

A MONGE-AMPÈRE TYPE MEASURE ASSOCIATED WITH $c$

Theorem. Let $\Omega$ be an open set in $\mathbb{R}^{n}$. Let $u: \Omega \rightarrow \mathbb{R} \cup\{+\infty\}$ be such that on any bounded open set $U \Subset \Omega, u$ is not identically $+\infty$ and bounded from below. Then the Lebesgue measure of the set
$S=\left\{p \in \mathbb{R}^{n}:\right.$ there exist $x, y \in \Omega, x \neq y$ and $\left.p \in \partial_{c} u(x) \cap \partial_{c} u(y)\right\}$
is zero.

Theorem. Suppose $c: \mathbb{R}^{n} \rightarrow \mathbb{R}$ is $C^{1}$ and strictly convex. Let $\Omega \subset \mathbb{R}^{n}$ be an open set, $u \in C(\Omega)$, and $\mathcal{B}=\{E \subset \Omega$ : $\partial_{c} u(E)$ is Lebesgue measurable\}. We have
(i) If $K \subset \Omega$ is compact, then $\partial_{c} u(K)$ is closed.

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(i) If $K \subset \Omega$ is compact, then $\partial_{c} u(K)$ is closed.
(ii) $\mathcal{B}$ contains all closed subsets of $\Omega$.
(iii) $\mathcal{B}$ is a $\sigma$-algebra on $\Omega$ containing all Borel subsets of $\Omega$. Moreover,

$$
\left|\partial_{c} u(\Omega \backslash E)\right|=\left|\partial_{c} u(\Omega) \backslash \partial_{c} u(E)\right| \quad \forall E \in \mathcal{B}
$$

## DEFINITION OF THE MONGE-AMPÈRE MEASURE ASSOCIATED WITH $c$

Let $g \in L_{\text {loc }}^{1}\left(\mathbb{R}^{n}\right)$ positive a.e. Suppose that $c$ is $C^{1}$ and strictly convex.

Then for each given function $u \in C(\Omega)$, the generalized MongeAmpère measure of $u$ associated with the cost function $c$ and the weight $g$ is the Borel measure defined by

$$
\omega_{c}(g, u)(E)=\int_{\partial_{c} u(E)} g(p) d p
$$

for every Borel set $E \subset \Omega$. When $g \equiv 1$, we simply write the measure as $\omega_{c}(u)$.

Suppose that $c$ is $C^{1}$ and strictly convex, and $c^{*} \in C^{2}\left(\mathbb{R}^{n}\right)$. Then If $u \in C^{2}(\Omega)$ is $c$-convex in $\Omega$, then

$$
\omega_{c}(g, u)(E)=\int_{E} g\left(x-D c^{*}(-D u)\right) \operatorname{det}\left(I+D^{2} c^{*}(-D u) D^{2} u\right) d x
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and the $c$-convex function $u \in C(\Omega)$ is a generalized solution in the sense of Aleksandrov, or simply Aleksandrov solution, if

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$$

for any Borel set $E \subset \Omega$.

If in the equation

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we set $c(x)=\frac{1}{2}|x|^{2}$, then $c^{*}(x)=\frac{1}{2}|x|^{2}$ and the equation becomes

$$
g(x+D u(x))) \operatorname{det}\left[I+D^{2} u(x)\right]=f(x) \text { in } \Omega
$$

that is, the Monge-Ampère equation for $\frac{1}{2}|x|^{2}+u(x)$.

## MAIN RESULTS

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$$
\begin{aligned}
& \text { for every open set } D \Subset \Omega \text { with }\left|\partial_{c} v\left(D \backslash \operatorname{spt}\left(\omega_{c}(u)\right)\right)\right|=0 \text {, } \\
& \exists \text { a closed set } F \subset \partial_{c} v(S \cap D) \text { such that }\left|\partial_{c} v(S \cap D) \backslash F\right|=0 \text {. }
\end{aligned}
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$$
\min _{\bar{\Omega}}\{u(x)-v(x)\}=\min _{\partial \Omega}\{u(x)-v(x)\}
$$

The condition before is satisfied if any of the following hold.

1. For each $D \Subset \Omega$ open, the set $S \cap D$ is closed.
2. If $\operatorname{stp}\left(\omega_{c}(u)\right)=\bar{V}$ with $V$ open subset of $\Omega$. In this case we have $S=\emptyset$.
3. If $\omega_{c}(v)=\sum_{i=1}^{N} a_{i} \delta_{x_{i}}$. Because in this case we have that for each $E \subset \Omega$ there exists $F$ compact such that $F \subset \partial_{c} v(E)$ and $\left|\partial_{c} v(E) \backslash F\right|=0$. Indeed, the set $E \cap\left\{x_{1}, \cdots, x_{N}\right\}$ is finite and $\partial_{c} v\left(E \cap\left\{x_{1}, \cdots, x_{N}\right\}\right)$ is compact and contained in $\partial_{c} v(E)$, and $\omega_{c}(v)(E)=\omega_{c}(v)\left(E \cap\left\{x_{1}, \cdots, x_{N}\right\}\right)$, so we let $F=\partial_{c} v\left(E \cap\left\{x_{1}, \cdots, x_{N}\right\}\right)$.

## SOLUTION OF THE HOMOGENEOUS DIRICHLET PROBLEM

Let $c: \mathbb{R}^{n} \rightarrow \mathbb{R}$ be a continuous function. A bounded set $E \subset \mathbb{R}^{n}$ is called strictly $c$-convex if for any $z \in \partial E$, any $\delta>0$ and any $a>0$, there exist $y, y^{*} \in \mathbb{R}^{n}$ such that

$$
\begin{aligned}
c(x-y)-c(z-y) & \geq 0 \forall x \in \partial E \\
c(x-y)-c(z-y) & \geq a \forall x \in \partial E-B(z, \delta) \\
c\left(z-y^{*}\right)-c\left(x-y^{*}\right) & \geq 0 \forall x \in \partial E \\
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If $\Omega \subset \mathbb{R}^{n}$ bounded open set satisfying the exterior sphere condition, then $\Omega$ is strictly $c$-convex.

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Theorem. Suppose that $c \in C^{1}\left(\mathbb{R}^{n}\right)$ and strictly convex. Let $\Omega \subset \mathbb{R}^{n}$ be a strictly c-convex open set and $\psi: \partial \Omega \rightarrow \mathbb{R}$ be a continuous function. Then there exists a unique c-convex function $u \in C(\bar{\Omega})$ Aleksandrov generalized solution of the problem

$$
\begin{aligned}
\operatorname{det}\left[I+D^{2} c^{*}(-D u(x)) D^{2} u(x)\right] & =0 \quad \text { in } \Omega \\
u & =\psi \text { on } \partial \Omega
\end{aligned}
$$

## SOLUTION OF THE NONHOMOGENEOUS DIRICHLET PROBLEM

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Then there exists a unique function $u \in C(\bar{\Omega}), c$-convex solution to the problem

$$
\begin{aligned}
\operatorname{det}\left[I+D^{2} c^{*}(-D u(x)) D^{2} u(x)\right] & =\sum_{i=1}^{N} a_{i} \delta_{x_{i}} \\
u & =\psi, \text { on } \partial \Omega .
\end{aligned}
$$

## VI

## IDEAS OF <br> THE PROOFS

## OUTLINE OF THE SOLUTION OF THE HOMOGENEOUS DP

Define
$\mathcal{F}:=\left\{f(x)=-c(x-y)-\lambda: y \in \mathbb{R}^{n}, \lambda \in \mathbb{R}\right.$ and $f(x) \leq \psi(x)$ on $\left.\partial \Omega\right\}$.
$\psi$ continuous on $\partial \Omega \Longrightarrow \mathcal{F} \neq \emptyset$

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$\psi$ continuous on $\partial \Omega \Longrightarrow \mathcal{F} \neq \emptyset$
Let

$$
u(x)=\sup \{f(x): f \in \mathcal{F}\}
$$

- Step 1: $u(x)=\psi(x) \quad \forall x \in \partial \Omega$.

This follows from the $c$-convexity of $\Omega$.

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- Step 2: $u$ is $c$-convex and $u \in C(\Omega)$.

Let $g(x):=-c(x)+\max _{\bar{\Omega}} c+\max _{\partial \Omega} \psi$. We have $g(x) \geq \psi(x)$ on $\partial \Omega, g$ is c-convex and as $c \in C^{1}\left(\mathbb{R}^{n}\right)$ we have $\partial_{c} g(\Omega)=\{0\}$ and so $\left|\partial_{c} g(\Omega)\right|=0$. Hence for each $f(x)=-c(x-y)-\lambda \in \mathcal{F}$, and applying the comparison principle we get $f(x) \leq g(x)$ in $\bar{\Omega}$ and therefore $u$ is uniformly bounded from above on $\bar{\Omega}$. Thus, we get $u$ is uniformly bounded on $\bar{\Omega}$. Particularly, this implies that $u$ is $c$-convex and moreover locally Lipschitz, so $u \in C(\Omega)$.

- Step 3: $u$ is continuous up to the boundary.

It follows from the $c$-convexity of $\Omega$ and the comparison principle.

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- Step 4: $\left|\partial_{c} u(\Omega)\right|=0$.

Let $p \in \partial_{c} u(\Omega)$. Then there exists $x_{0} \in \Omega$ such that

$$
u(x) \geq u\left(x_{0}\right)-c(x-p)+c\left(x_{0}-p\right)=f(x) \quad \forall x \in \Omega
$$

There exists $\zeta \in \partial \Omega$ satisfying $f(\zeta)=\psi(\zeta)$.
Then $p \in \partial_{c}(u, \bar{\Omega})\left(x_{0}\right) \cap \partial_{c}(u, \bar{\Omega})(\zeta)$ but this is a set of measure zero.

## OUTLINE OF THE SOLUTION OF THE NONHOMOGENEOUS DP

- Let

$$
\begin{aligned}
& \mathcal{H}=\left\{v \in C(\bar{\Omega}): v \text { is } c \text {-convex in } \Omega,\left.v\right|_{\partial \Omega}=\psi\right. \\
& \left.\qquad\left|\partial_{c} v(\Omega)\right|=\sum_{i=1}^{N}\left|\partial_{c} v\left(x_{i}\right)\right|, \text { and }\left|\partial_{c} v\left(x_{i}\right)\right| \leq a_{i} \text { for } i=1 \leq i \leq N\right\}
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$$

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Let $W$ be the solution to $\omega_{c}(W)=0$ and $W=\psi$ on $\partial \Omega$.
We have $W \in \mathcal{H}$, and from the comparison principle

$$
v \leq W, \text { for each } v \in \mathcal{H}
$$

For each $v \in \mathcal{H}$ define

$$
V[v]=\int_{\Omega}(W(x)-v(x)) d x \geq 0
$$

and let

$$
\beta=\sup _{v \in \mathcal{H}} V[v] .
$$

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$$
\beta=\sup _{v \in \mathcal{H}} V[v] .
$$

- IDEA: there exists $u \in \mathcal{H}$ such that $\beta=V[u]$ and $u$ is the desired solution to the nonhomogeneous DP.
- There exists a convex function $w \in C(\bar{\Omega})$ with $w=\psi$ on $\partial \Omega$ and

$$
w(x) \leq v(x), \quad \text { in } \bar{\Omega} \text { and for all } v \in \mathcal{H}
$$

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$$
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$$

Assume $\Omega$ is strictly convex, from the solution of the DP for the standard Monge-Ampère equation, there exists $w \in C(\bar{\Omega})$ convex in $\Omega$ solving in the weak sense

$$
\begin{aligned}
\operatorname{det} D^{2} w & =\lambda_{1} \delta_{x_{1}}+\cdots+\lambda_{N} \delta_{x_{N}} \\
w & =\psi \text { on } \partial \Omega
\end{aligned}
$$

for any $\lambda_{i}>0, i=1, \cdots, N$. The $\lambda_{i}$ 's are chosen appropriately.

We have $\beta \leq V[w]<\infty$. Then there exists a sequence $\left\{u_{n}\right\} \subset \mathcal{H}$ such that $V\left[u_{n}\right] \uparrow \beta$ as $n \rightarrow \infty$. From the estimates we have that

$$
w(x) \leq u_{n}(x) \leq W(x), \quad \forall x \in \bar{\Omega}
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$$
w(x) \leq u_{n}(x) \leq W(x), \quad \forall x \in \bar{\Omega}
$$

- There is a subsequence $\left\{u_{n_{k}}\right\}$ and $u \in C(\bar{\Omega})$ with $u=\psi$ on $\partial \Omega$ and $u_{n_{k}} \rightarrow u$ locally uniformly in $\Omega$ as $k \rightarrow \infty$.
$u$ IS THE SOLUTION WE LOOK FOR!


## VII

FINAL REMARKS

The second boundary value problem for the Monge-Ampère type operators arises in optimal transportation

$$
\begin{aligned}
g\left(x-D c^{*}(-D u(x))\right) \operatorname{det}\left[I+D^{2} c^{*}(-D u(x)) D^{2} u(x)\right] & =f(x) \text { in } \Omega_{1} \\
\partial_{c} u\left(\Omega_{1}\right) & =\Omega_{2}
\end{aligned}
$$

A $c$-convex function $u \in C\left(\Omega_{1}\right)$ is called a Brenier solution of the second BV problem if

$$
\int_{\Omega_{1}} h(s(x)) f(x) d x=\int_{\Omega_{2}} h(y) g(y) d y, \quad \text { for all } h \in C\left(\mathbb{R}^{n}\right)
$$

or equivalently,

$$
\int_{s^{-1}(E)} f(x) d x=\int_{E \cap \Omega_{2}} g(y) d y, \quad \text { for all Borel sets } E \subset \mathbb{R}^{n}
$$

where $s: \Omega_{1} \rightarrow \mathbb{R}^{n}$ is a Borel measurable map defined a.e. on $\Omega_{1}$ by the formula $s(x)=x-D c^{*}(-D u(x))$ whenever $u$ is differentiable at $x$.

Lemma. . If $u$ is an Aleksandrov solution, then $u$ is also a Brenier solution.

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## Conversely,

Theorem. Let $\Omega_{1}, \Omega_{2}$ be bounded domains in $\mathbb{R}^{n}$ such that $\Omega_{2}$ is $c^{*}$-convex relative to $\Omega_{1}$. Suppose $u \in C\left(\Omega_{1}\right)$ is a c-convex function on $\Omega_{1}$ Brenier solution of the second $B V$ problem, then $u$ is an Aleksandrov solution.

