

Consensus and Flocking in Self-Alignment Dynamics

Lecture II. Consensus and flocking

Eitan Tadmor

Center for Scientific Computation and Mathematical Modeling (CSCAMM)
Department of Mathematics, Institute for Physical Science & Technology
University of Maryland

www.cscamm.umd.edu/tadmor

School “Luis Santaló”: Scientific Challenges in a Sustainable Planet
UIMP, Santander, July 15-19 2013

Mathematical considerations

- By L_A we denote the **Laplacian** matrix associated with $A = \{a_{ij}\}$

$$L_A := D - A, \quad D_{ii} = \sum_j a_{ij} \leftarrow \text{deg}_i$$

- Self-alignment is driven by a discrete Laplacian ($\alpha \mapsto 1$):

$$\frac{d}{dt} \mathbf{p}_i(t) = \alpha \sum_j a_{ij} (\mathbf{p}_j - \mathbf{p}_i) \mapsto \sum_j a_{ij} \mathbf{p}_j - \text{deg}_i \mathbf{p}_i \leftrightarrow \frac{d}{dt} \mathbf{p} = -L_A \mathbf{p}$$

Observe that $\text{Re} \lambda_k(L_A) \geq 0$ and $L_A \mathbf{1} = 0$, $\mathbf{1} = (1, 1, \dots, 1)^\top$.

In particular, if A is symmetric $\lambda(A) \geq 0$:

\mapsto Symmetric A 's: $0 = \lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_N$

- ⊙ The example of the “usual” Laplacian matrix

$$\left\{ \dots \frac{1}{4}, \dots, \frac{1}{4}, -1, \frac{1}{4}, \dots, \frac{1}{4}, \dots \right\}$$

- ⊙ Note the issue of a **sign** – the Laplacian should be negative:
 $(\Delta u, u) = -|\nabla u|^2 \leq 0$ and not positive $\langle L_A u, u \rangle \geq 0$

Mathematical considerations cont'd

- Self-alignment: $\frac{d}{dt} \mathbf{p} = -L_A \mathbf{p} \rightsquigarrow \frac{1}{2} \frac{d}{dt} |\mathbf{p}|^2 = -\langle L_A \mathbf{p}, \mathbf{p} \rangle \leq 0$
which is consistent with **convexity** ($\rightsquigarrow \mathbf{p}(t) \in \text{conv hull}\{\mathbf{p}_j\}$)
but lacks coercivity: $-\langle L_A \mathbf{p}, \mathbf{p} \rangle \not\leq -|\mathbf{p}|^2$
- Operators on graphs: “nodes” $\{\mathbf{p}\}_i \in X$ and “edges” $\{\mathbf{u}\}_{ij} \in Y$
gradient $\nabla : X \mapsto Y : (\nabla \mathbf{p})_{ij} := \sqrt{a_{ij}}(p_j - p_i)$
divergence $\text{div} : Y \mapsto X : (\text{div } \mathbf{u})_i := \sum_j \sqrt{a_{ij}}(u_{ji} - u_{ij})$

\rightsquigarrow with the usual duality: $\langle \nabla \mathbf{p}, \mathbf{u} \rangle = \langle \mathbf{p}, \text{div } \mathbf{u} \rangle$ for **symmetric** A 's

- Self-alignment: $\frac{d}{dt} \mathbf{p} = \text{div } \nabla \mathbf{p} \rightsquigarrow \frac{1}{2} \frac{d}{dt} |\mathbf{p}|^2 = -|\nabla \mathbf{p}|^2:$

$$\frac{1}{2} \frac{d}{dt} \sum_i |\mathbf{p}_i|^2 = -\frac{1}{2} \sum_{ij} a_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2 \leq 0$$

- And since $\sum_i \mathbf{p}_i(t) = \sum_i \mathbf{p}_i(0)$:

$$\frac{1}{2N} \frac{d}{dt} \sum_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2 = -\sum_{ij} a_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2$$

Mathematical considerations cont'd

- **Exercise:** $\frac{d}{dt} \mathbf{p}_i = \sum_j a_{ij} (\mathbf{p}_j - \mathbf{p}_i)$ with symmetric A 's —

$$\rightsquigarrow \frac{1}{2N} \frac{d}{dt} \sum_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2 = - \sum_{ij} a_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2$$

- What about coercivity — $\text{RHS} \lesssim - \sum_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2$?

For example, $-\sum_{ij} a_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2 \leq -\min a_{ij} \sum_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2$ implies

$$\frac{d}{dt} \sum_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2 \leq -\eta \sum_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2, \quad \eta = 2N \min a_{ij}$$

- **Sharp** characterization – Courant-Fischer (for symmetric A 's):

$$\lambda_2(L_A) = \min_{\sum \mathbf{p}_k = 0} \frac{\langle L_A \mathbf{p}, \mathbf{p} \rangle}{|\mathbf{p}|^2} \leq N \frac{\sum_{ij} a_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2}{\sum_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2}$$

$$\rightsquigarrow - \sum_{ij} a_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2 \leq \frac{1}{N} \lambda_2(L_A) \sum_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2$$

Mathematical considerations – spectral analysis

$$\frac{1}{2} \frac{d}{dt} \sum_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2 \leq -\lambda_2(L_A) \sum_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2$$

↪ Convergence towards flocking/consensus is dictated by the **the Fiedler number**:

$$\frac{d}{dt} V(t) \lesssim -\lambda_2(L_{A(t)}) V(t), \quad V_{\mathbf{p}(t)}^2 = \frac{1}{N^2} \sum_{ij} |\mathbf{p}_i(t) - \mathbf{p}_j(t)|^2$$

Exercise: verify the last few steps...

- sharp characterization: $\lambda_2(L_A) \geq N \min_{ij} a_{ij}$

Questions:

- What about the Fiedler number $\lambda_2(L_A)$?
- What about the non-symmetric models of self-alignment?

The symmetric case: spectral analysis

- Convergence towards flocking/consensus is dictated by

$$\frac{d}{dt}V(t) \lesssim -\lambda_2(L_{A(t)})V(t), \quad V_{\mathbf{p}(t)}^2 = \frac{2}{N^2} \sum_{ij} |\mathbf{p}_i(t) - \mathbf{p}_j(t)|^2$$
$$V_{\mathbf{p}(t)}^2 = \frac{1}{N} \sum_i |\mathbf{p}_i - \langle \mathbf{p} \rangle|^2, \quad \langle \mathbf{p} \rangle(t) = \frac{1}{N} \sum_k \mathbf{p}_k \equiv \langle \mathbf{p} \rangle(0)$$

$$|\mathbf{p}_i(t) - \langle \mathbf{p} \rangle(0)| \lesssim e^{-\alpha \eta t} V_{\mathbf{p}(0)}, \quad \eta := \min_t \lambda_2(L_A(\mathbf{p}(t)))$$

- Flocking/consensus if $\eta = \min_t \lambda_2(L_A(\mathbf{p}(t))) > 0$ or at least ...

$$\lambda_2(s) \equiv \lambda_2(L_{A(\mathbf{p}(s))}) \int_0^\infty \lambda_2(s) ds = \infty \rightsquigarrow \text{flocking/consensus}$$

- Fiedler number $\lambda_2(L_A)$ quantifies **algebraic connectivity**:

$\mathcal{G}_A = \{\mathbf{p}, A(\mathbf{p})\}$ is uniformly connected if every two agents are connected through a path, $\Gamma_{ij} = \{k_1 = i < k_2 < \dots < k_r = j\}$

$$\forall \text{ pairs } (\mathbf{p}_i, \mathbf{p}_j) : \exists \Gamma_{ij} \text{ such that } \min_{k_\ell \in \Gamma_{ij}} a_{(k_\ell, k_{\ell+1})} \geq \mu > 0$$

Consensus/flocking by the “energy method”

$$\frac{d\mathbf{p}_i}{dt} = \alpha \sum_{j \neq i} a_{ij}(\mathbf{p}_j - \mathbf{p}_i), \quad \text{stochastic adjacency matrix } \sum_j a_{ij} = 1$$

- Contraction of diameters: $d_{\mathbf{p}}(t) := \max_{i,j} |\mathbf{p}_i(t) - \mathbf{p}_j(t)|$
 $\frac{d}{dt} d_{\mathbf{p}}(t) \leq -\alpha (\min_{ij} \eta_{ij}) d_{\mathbf{p}}(t), \quad \eta_{ij} := \sum_k \min(a_{ik}, a_{jk})$

- If $\eta = \min_{ij} \eta_{ij} > 0$ then $\exists \mathbf{p}^\infty \in \text{conv}(\{\mathbf{p}_i\})$ s.t.

$$|\mathbf{p}_i(t) - \mathbf{p}^\infty| \lesssim e^{-\alpha \eta t} d_{\mathbf{p}}(0), \quad \eta := \min_{ij} \sum_k \min(a_{ik}, a_{jk})$$

DeGroot, Chatterjee, Krause, ... Motsch & ET

- **Unconditional flocking** using $\ell_1, \ell_2, \ell_\infty$ - based approaches:
Cucker & Smale, Ha & ET, Carrillo et. al., Ha & Liu,
- An ℓ_∞ “energy method – covers non-symmetric models

The energy method vs. spectral analysis

$$|\mathbf{p}_i(t) - \mathbf{p}^\infty| \lesssim e^{-\alpha\eta t} d_{\mathbf{p}(0)}, \quad \eta := \min_{ij} \sum_k \min(a_{ik}, a_{jk})$$

- Consensus if $\eta(t) > N \min_{ij} a_{ij} > 0$ – requires **global interactions** or at least one neighbor connectivity (the symmetric case)
- Spectral analysis of the symmetric case:

$$|\mathbf{p}_i(t) - \mathbf{p}^\infty| \lesssim e^{-\alpha\eta t} V_{\mathbf{p}(0)}, \quad \eta := \min_t \lambda_2(L_A(\mathbf{p}(t)))$$

- If $\eta = \min_t \lambda_2(L_A(\mathbf{p}(t))) > 0$ – requires **connectivity of graph** or sufficiently strong influence $\int_0^\infty \eta(s) ds = \infty \rightsquigarrow$ flocking/consensus
- What is the consensus \mathbf{p}^∞ ? – by convexity: $\mathbf{p}^\infty \in \text{conv}(\{\mathbf{p}_i\})$
 - ⊙ Symmetric case: $\mathbf{p}^\infty = \langle \mathbf{p} \rangle(0)$, $\langle \mathbf{p} \rangle := \frac{1}{N} \sum_i \mathbf{p}_i$
 - ⊙ Non-symmetric case?

Global influence implies unconditional consensus

- Opinion dynamics —

$$\frac{d}{dt}x_i(t) = \alpha \sum_{j \neq i} a_{ij}(x_j - x_i), \quad a_{ij} = \frac{1}{\text{deg}_i} \phi(|x_i - x_j|), \quad \text{deg}_i = \left\{ \begin{array}{l} N \\ \sum_k \phi_{ik} \end{array} \right.$$

- $\eta = N \min_{ij} a_{ij} \mapsto N \min_{ij} \frac{1}{\text{deg}_i} \phi(|x_i - x_j|) \geq \min_{r \leq d_x(t)} \phi(r)$:

and since $d_x(t) \leq d_x(0)$:

$$\frac{d}{dt}d_x(t) \leq -\alpha\eta d_x(t), \quad \eta = \min_{r \leq d_x(0)} \phi(r) > 0$$

- Set $\text{Supp}\{\phi(\cdot)\} = [0, \rho)$:

$$\rho > d_x(0) \mapsto |x_i(t) - x^\infty| \lesssim e^{-\alpha\eta t}, \quad x^\infty \in \text{conv}(\{x_i\})$$

- Global interactions \mapsto unconditional emergence of consensus

Global influence implies unconditional flocking

- Flocking dynamics —

$$\frac{d}{dt} v_i(t) = \alpha \sum_{j \neq i} a_{ij} (v_j - v_i), \quad a_{ij} = \frac{1}{\text{deg}_i} \phi(|x_i - x_j|), \quad \text{deg}_i = \left\{ \begin{array}{l} N \\ \sum_k \phi_{ik} \end{array} \right.$$

- $\phi(0) = 1 \searrow$: $\eta \equiv \eta(t) \geq N \min \frac{1}{\text{deg}_i} \phi(|x_i - x_j|) \geq \phi(d_x(t))$

$$\frac{d}{dt} d_v(t) \leq -\alpha \phi(d_x(t)) d_v(t), \quad \frac{d}{dt} d_x(t) \leq d_v(t)$$

[S.-Y Ha & J.-G Liu] $\mathcal{E}(t) := d_v(t) + \alpha \int_0^{d_x(t)} \phi(s) ds \downarrow$

- If $\int_0^\infty \phi(s) ds > d_v(0)$ implies bounded expansion: $d_x(t) \leq R$

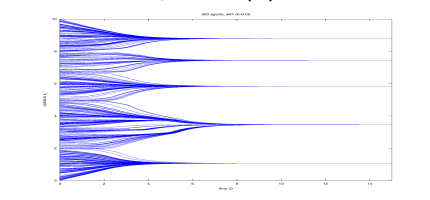
$$\int_0^\infty \phi(s) ds > d_v(0) \quad \mapsto \quad |v_i(t) - v^\infty| \lesssim e^{-\alpha \eta t}, \quad \eta := \phi(R)$$

- Example: $\phi(r) = \frac{1}{1+r^{2\beta}}$: unconditional flocking if $\beta \leq 1/2$
- Global interactions ($\rho > d_x(0)$) implies emergence of flocking

Cucker-Smale vs. the new model

Local interactions — the emergence of clusters

- If ϕ is compactly supported: $\rho < d_x(0) \mapsto$ formation of clusters:



- A cluster $\mathcal{C} \subset \{1, 2, \dots, N\}$:
$$\begin{cases} \#1. & \max_{i,j \in \mathcal{C}} |x_i - x_j| \leq \rho; \\ \#2. & \min_{i \in \mathcal{C}, j \notin \mathcal{C}} |x_i - x_j| > \rho \end{cases}$$

- Self-contained dynamics:
$$\frac{d}{dt} \mathbf{p}_{i \in \mathcal{C}} = \sum_{j \in \mathcal{C}} a_{ij} (\mathbf{p}_j - \mathbf{p}_i), \quad \sum_{j \in \mathcal{C}} a_{ij} = 1$$

- If $\mathbf{p}(t) \in BV$ then $\exists \mathbf{p}^\infty$, partitioned into finitely many clusters:

$$\{1, 2, \dots, N\} = \cup_{k=1}^K \mathcal{C}_k : \begin{cases} \text{either } \mathbf{p}_i(t) \rightarrow \mathbf{p}_{\mathcal{C}_k}^\infty, & \forall i \in \mathcal{C}_k \\ \text{or } |x_i^\infty - x_j^\infty| > \rho, & i \in \mathcal{C}_k, j \in \mathcal{C}_\ell, k \neq \ell. \end{cases}$$

Question #1 Determine K_∞ based on $\{\mathbf{p}\}(0)$ and ϕ ?

Question #2 $K_\infty = 1$? —that is, consensus of local interactions?

Connectivity is necessary and sufficient for consensus

- $\mathcal{G}_A = \{\mathbf{p}, A(\mathbf{p})\}$ is uniformly connected if every two agents are connected through a path, $\Gamma_{ij} = \{k_1 = i < k_2 < \dots < k_r = j\}$

$$\forall \mathbf{p}_i, \mathbf{p}_j, \exists \Gamma_{ij} \text{ such that } \min_{k_\ell \in \Gamma_{ij}} a_{(k_\ell, k_{\ell+1})} \geq \mu > 0$$

- Clearly, connectivity is necessary for flocking/consensus ... and it is also sufficient for flocking/consensus:
- Symmetric models: $L_A := I - A$ graph Laplacian of A with e.v. $0 = \lambda_1(L_A) \leq \lambda_2(L_A) \leq \dots \leq \lambda_N(L_A) \leq 1$

$$V(t) \leq e^{-\alpha \lambda_2 t} V(0), \quad V^2(t) := \frac{1}{N} \sum_i |\mathbf{p}_i(t) - \langle \mathbf{p} \rangle(0)|^2$$

If \mathcal{G}_A is connected then: $\lambda_2(L_A) \geq \frac{\mu}{N^2} \mapsto$ consensus/flocking

Connectivity is sufficient for consensus – cont'd

- The symmetric case: Let $diam(\mathcal{G}_A) = \max_{ij} \text{length}(\Gamma_{ij})$, then

$$|\mathbf{p}_i - \mathbf{p}_j|^2 \leq diam(\mathcal{G}_A) \sum_{k_\ell \in \Gamma_{ij}} |\mathbf{p}_{k_{\ell+1}} - \mathbf{p}_{k_\ell}|^2;$$

By uniform connectivity

$$\frac{\mu}{diam(\mathcal{G}_A)} |\mathbf{p}_i - \mathbf{p}_j|^2 \leq \sum_{k_\ell \in \Gamma_{ij}} a_{k_{\ell+1}, k_\ell} |\mathbf{p}_{k_{\ell+1}} - \mathbf{p}_{k_\ell}|^2 \leq \sum_{ij} a_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2$$

and hence (“coercivity with vanishing entries”)

$$\lambda_2(L_A) = \min_{\mathbf{p}} N \frac{\sum_{ij} a_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2}{\sum_{ij} |\mathbf{p}_i - \mathbf{p}_j|^2} \geq \frac{\mu}{N diam(\mathcal{G}_A)} \geq \frac{\mu}{N^2}$$

Exercise Work out the details.

- If connectivity persists — $\lambda_2(L_{A(\mathbf{p}(s))}) > 0 \rightsquigarrow$ consensus

Question: Trace the propagation of connectivity in time: $\lambda_2(L_{A(\mathbf{p}(t))})$

- If $diam(\mathcal{G}_A) = 1$ then by the ℓ_∞ -energymethod: $\lambda_2(L_A) \geq \mu$.

Connectivity is sufficient for consensus – cont'd

- The example of non-symmetric opinion dynamic (e.g., Krause model):

$$\dot{x}_i = \frac{\alpha}{\deg_i} \sum_j \phi_{ij}(x_j - x_i), \quad \deg_i = \sum_j \phi_{ij}, \quad \phi_{ij} \equiv \phi(|x_i - x_j|)$$

- An energy method — the “energy” $\mathcal{E}(t)$ decays:

$$\mathcal{E}(t) := \sum_{ij} \Phi(|x_i - x_j|), \quad \Phi(r) = \int_0^r s\phi(s)ds$$

satisfies $\frac{d}{dt}\mathcal{E}(t) \lesssim - \left(\sum_{ij} \phi_{ij}|x_i - x_j|^2 \right)^2 \lesssim \mathcal{E}^2(t)$ (coercivity)

If \mathcal{G}_A is connected then: $\mu d_{\mathbf{x}}(t) \lesssim \frac{1}{\sqrt{t}} \mapsto$ consensus after $t \geq t_0$

On the propagation of connectivity

- Consensus \mapsto connectivity
- Connectivity \mapsto consensus

How the influence function dictates persistence of connectivity?

- Heterophilious dynamics:

“Similarity breeds connectivity”: intuition tells us about ...
Tendency to align with those that act and think alike:

Homophilious — $a_{ij} \sim \frac{1}{\text{deg}_i} \phi(|x_i(t) - x_j(t)|)$ with $\phi \downarrow$

Heterophilious — “bonding with the different”:

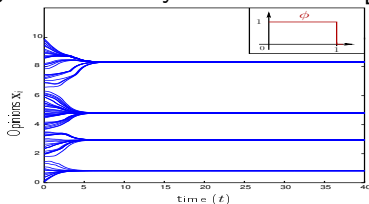
$a_{ij} \sim \frac{1}{\text{deg}_i} \phi(|x_i(t) - x_j(t)|)$ with $\phi \uparrow$

- Nearest neighbor dynamics:

Motivated by the careful observations of Rome group:
the influencing neighborhood is topological not geometrical

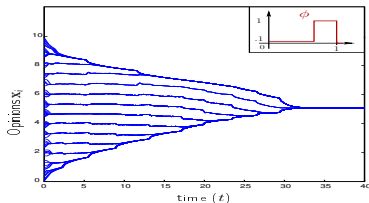
1D Heterophilious dynamics

- Strong influence: $1.0\chi_{\{0 \leq r < 1\}}$, $\phi(r) \searrow$
- Consensus: 100 agents uniformly distributed on $[0, 10]$.



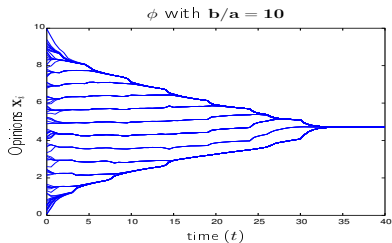
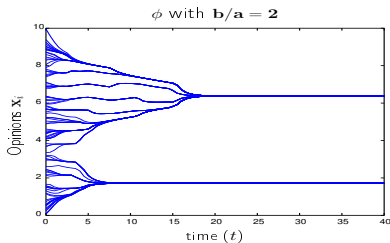
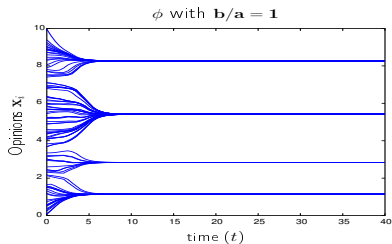
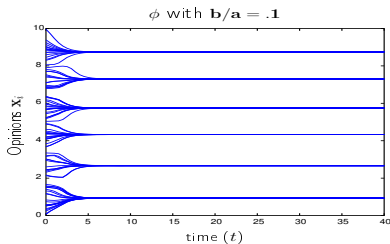
Strong influence \mapsto fragmentation into clusters

- “Weak” influence: $\phi(r) = 0.1\chi_{\{r \leq \frac{1}{\sqrt{2}}\}} + 1 \cdot \chi_{\{\frac{1}{\sqrt{2}} \leq r < 1\}}$, $\phi(r) \nearrow$



Heterophily influence \mapsto connectivity and hence consensus!!

More on heterophilious dynamics

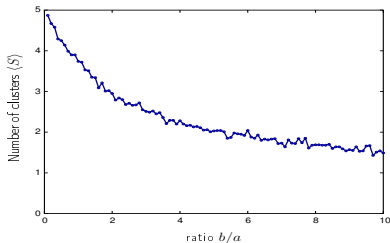


Opinion dynamics with different $\phi = a\chi_{[0, \frac{1}{\sqrt{2}}]} + b\chi_{[\frac{1}{\sqrt{2}}, 1]}$. Reducing the relative influence of close neighbors (as $b/a \uparrow$), decreases the # of clusters. For $b/a = 10$, the dynamics converges to a consensus.

Heterophilipus dynamics and the decrease of # of clusters

- This was not a coincidence:

Trace the propagation of connectivity in time: # clusters $K(t)$:



Log decay of average number of clusters $\langle K \rangle$ depending on the ratio b/a . For each b/a , we run 100 simulations to estimate $\langle K \rangle$.

2D Heterophilious dynamics

- Local interaction – compactly supported influence function ϕ
vs. Local interaction - heterophily dynamics with factor 10:

1D dynamics with nearest neighbor

- Interaction with two nearest neighbors (1D):

$$\frac{d}{dt}x_i(t) = \sum_{|i-j|=1} \phi_{ij}(x_j - x_i), \quad \phi_{ij} = \phi(|x_i - x_j|)$$

THM. If ϕ is **non-decreasing** on $d_{\mathbf{x}}(0)$, then the graph remains connected and $|x_i(t) - \bar{x}| \lesssim e^{-\gamma t/N^2} |x_i(0) - \bar{x}|$

- A steeper increase of ϕ enhances the connectivity ...