Average conditions for permanence in *N*-species nonautonomous competitive systems of PDEs.

Joanna Balbus

Institute of Mathematics and Computer Science Wrocław University of Technology Wrocław, Poland

BIOMAT 2013 Evolution and cooperation in social sciences and biomedicine, Granada, June 20 2013

By the nonautonomous competitive system of partial differential equations (PDEs) of Kolmogorov type we mean the system

$$\begin{cases} \frac{\partial u_i}{\partial t} = \mu_i \Delta u_i + f_i(t, x, u_1, \dots, u_N) u_i, & t > 0, \ x \in \Omega, \ i = 1, \dots, N \\ \mathcal{B}_i u_i = 0, & t > 0, \ x \in \partial \Omega, \ i = 1, \dots, N \\ (\mathsf{R}) \end{cases}$$

By the nonautonomous competitive system of partial differential equations (PDEs) of Kolmogorov type we mean the system

$$\begin{cases} \frac{\partial u_i}{\partial t} = \mu_i \Delta u_i + f_i(t, x, u_1, \dots, u_N) u_i, & t > 0, \ x \in \Omega, \ i = 1, \dots, N \\ \mathcal{B}_i u_i = 0, & t > 0, \ x \in \partial \Omega, \ i = 1, \dots, N \\ (\mathsf{R}) \end{cases}$$

• $u_i(t, x)$ – population density of the *i*-th species at time *t* and spatial location $x \in \overline{\Omega}$,

By the nonautonomous competitive system of partial differential equations (PDEs) of Kolmogorov type we mean the system

$$\begin{cases} \frac{\partial u_i}{\partial t} = \mu_i \Delta u_i + f_i(t, x, u_1, \dots, u_N) u_i, & t > 0, \ x \in \Omega, \ i = 1, \dots, N\\ \mathcal{B}_i u_i = 0, & t > 0, \ x \in \partial \Omega, \ i = 1, \dots, N \end{cases}$$
(R)

- u_i(t, x) population density of the *i*-th species at time t and spatial location x ∈ Ω
- $\Omega \subset \mathbb{R}^n$ bounded habitat,

By the nonautonomous competitive system of partial differential equations (PDEs) of Kolmogorov type we mean the system

$$\begin{cases} \frac{\partial u_i}{\partial t} = \mu_i \Delta u_i + f_i(t, x, u_1, \dots, u_N) u_i, & t > 0, \ x \in \Omega, \ i = 1, \dots, N\\ \mathcal{B}_i u_i = 0, & t > 0, \ x \in \partial \Omega, \ i = 1, \dots, N\\ (\mathsf{R}) \end{cases}$$

 u_i(t, x) – population density of the *i*-th species at time t and spatial location x ∈ Ω

•
$$\Omega \subset \mathbb{R}^n$$
 – bounded habitat,

• $\mu_i > 0$ – migration rate of the *i*-th species,

By the nonautonomous competitive system of partial differential equations (PDEs) of Kolmogorov type we mean the system

$$\begin{cases} \frac{\partial u_i}{\partial t} = \mu_i \Delta u_i + f_i(t, x, u_1, \dots, u_N) u_i, & t > 0, \ x \in \Omega, \ i = 1, \dots, N \\ \mathcal{B}_i u_i = 0, & t > 0, \ x \in \partial \Omega, \ i = 1, \dots, N \\ (\mathsf{R}) \end{cases}$$

 u_i(t, x) – population density of the *i*-th species at time t and spatial location x ∈ Ω

•
$$\Omega \subset \mathbb{R}^n$$
 – bounded habitat,

- $\mu_i > 0$ migration rate of the *i*-th species,
- f_i(t, x, u₁, ..., u_N) local per capita growth rate of the *i*-th species,

By the nonautonomous competitive system of partial differential equations (PDEs) of Kolmogorov type we mean the system

$$\begin{cases} \frac{\partial u_i}{\partial t} = \mu_i \Delta u_i + f_i(t, x, u_1, \dots, u_N) u_i, & t > 0, \ x \in \Omega, \ i = 1, \dots, N \\ \mathcal{B}_i u_i = 0, & t > 0, \ x \in \partial \Omega, \ i = 1, \dots, N \\ (\mathsf{R}) \end{cases}$$

• $u_i(t, x)$ – population density of the *i*-th species at time *t* and spatial location $x \in \overline{\Omega}$,

•
$$\Omega \subset \mathbb{R}^n$$
 – bounded habitat,

- $\mu_i > 0$ migration rate of the *i*-th species,
- f_i(t, x, u₁, ..., u_N) local per capita growth rate of the *i*-th species,
- *B_i* is the Neumann boundary operator, or the Dirichlet boundary operator or the Robin boundary operator.

Denote by λ_i the *principal eigenvalue* of the elliptic eigenproblem

$$\begin{cases} \Delta \varphi_i + \lambda_i \varphi_i = 0 & \text{on } \Omega, \\ \mathcal{B}_i \varphi_i = 0 & \text{on } \partial \Omega \end{cases}$$

If we have Dirichlet boundary conditions then $\lambda_i > 0$. By the standard elliptic maximum principles a *principal eigenfunction* φ_i corresponding to λ_i can be chosen so that $\varphi_i(x) > 0$ for all $x \in \Omega$. We assume that φ_i is normalized so that $\max_{x \in \overline{\Omega}} \varphi_i(x) = 1$. In the Neumann boundary conditions we have $\lambda_i = 0$ and $\varphi_i \equiv 1$.

Definition

The solution $u(t,x) = (u_1(t,x), \ldots, u_N(t,x))$ of (R) is positive if $u_i(t,x) > 0$ for all $i = 1, \ldots, N$, $t \in (0, \tau_{max})$ and $x \in \Omega$.

Definition

The solution $u(t,x) = (u_1(t,x), \ldots, u_N(t,x))$ of (R) is positive if $u_i(t,x) > 0$ for all $i = 1, \ldots, N$, $t \in (0, \tau_{max})$ and $x \in \Omega$.

Now we introduce the following assumptions for a function f_i

Definition

The solution $u(t,x) = (u_1(t,x), \ldots, u_N(t,x))$ of (R) is positive if $u_i(t,x) > 0$ for all $i = 1, \ldots, N$, $t \in (0, \tau_{max})$ and $x \in \Omega$.

Now we introduce the following assumptions for a function f_i (A1) $f_i: [0,\infty) \times \overline{\Omega} \times [0,\infty)^N \to \mathbb{R}$ $(1 \le i \le N)$, as well as their first derivatives $\partial f_i / \partial t$ $(1 \le i \le N)$, $\partial f_i / \partial u_j$ $(1 \le i, j \le N)$, and $\partial f_i / \partial x_k$ $(1 \le i \le N, 1 \le k \le n)$, are continuous.

Definition

The solution $u(t,x) = (u_1(t,x), \ldots, u_N(t,x))$ of (R) is positive if $u_i(t,x) > 0$ for all $i = 1, \ldots, N$, $t \in (0, \tau_{max})$ and $x \in \Omega$.

Now we introduce the following assumptions for a function f_i

- (A1) $f_i: [0,\infty) \times \overline{\Omega} \times [0,\infty)^N \to \mathbb{R} \ (1 \le i \le N)$, as well as their first derivatives $\partial f_i / \partial t \ (1 \le i \le N)$, $\partial f_i / \partial u_j \ (1 \le i, j \le N)$, and $\partial f_i / \partial x_k \ (1 \le i \le N, \ 1 \le k \le n)$, are continuous.
- (A2) The functions $[[0,\infty) \times \overline{\Omega} \ni (t,x) \mapsto f_i(t,x,0,\ldots,0) \in \mathbb{R}], 1 \le i \le N$, are bounded.

Definition

The solution $u(t,x) = (u_1(t,x), \ldots, u_N(t,x))$ of (R) is positive if $u_i(t,x) > 0$ for all $i = 1, \ldots, N$, $t \in (0, \tau_{max})$ and $x \in \Omega$.

Now we introduce the following assumptions for a function f_i

- (A1) $f_i: [0,\infty) \times \overline{\Omega} \times [0,\infty)^N \to \mathbb{R} \ (1 \le i \le N)$, as well as their first derivatives $\partial f_i / \partial t \ (1 \le i \le N)$, $\partial f_i / \partial u_j \ (1 \le i, j \le N)$, and $\partial f_i / \partial x_k \ (1 \le i \le N, \ 1 \le k \le n)$, are continuous.
- (A2) The functions $[[0,\infty) \times \overline{\Omega} \ni (t,x) \mapsto f_i(t,x,0,\ldots,0) \in \mathbb{R}], 1 \le i \le N$, are bounded.

For $1 \le i \le N$ the function $f_i(t, x, 0, ..., 0)$ is called the intrinsic growth rate of the *i*-th species.

くほう くほう くほう

$$\underline{a}_{i} := \inf\{f_{i}(t, x, 0, \dots, 0) : t \ge 0, x \in \overline{\Omega}\},\\ \overline{a}_{i} := \sup\{f_{i}(t, x, 0, \dots, 0) : t \ge 0, x \in \overline{\Omega}\}.$$

・ロン ・部と ・ヨン ・ヨン

÷.

$$\underline{a}_{i} := \inf\{f_{i}(t, x, 0, \dots, 0) : t \ge 0, x \in \overline{\Omega}\},\\ \overline{a}_{i} := \sup\{f_{i}(t, x, 0, \dots, 0) : t \ge 0, x \in \overline{\Omega}\}.$$

Note that we do not assume here that $\underline{a}_i > 0$.

▶ < ∃ ▶</p>

э

э

$$\underline{a}_{i} := \inf\{f_{i}(t, x, 0, \dots, 0) : t \ge 0, x \in \overline{\Omega}\},\\ \overline{a}_{i} := \sup\{f_{i}(t, x, 0, \dots, 0) : t \ge 0, x \in \overline{\Omega}\}.$$

Note that we do not assume here that $\underline{a}_i > 0$. (A3) $(\partial f_i / \partial u_j)(t, x, u) \leq 0$ for all $t \geq 0$, $x \in \overline{\Omega}$, $u \in [0, \infty)^N$, $1 \leq i, j \leq N$, $i \neq j$.

 $(\partial f_i/\partial u_j)(t, x, u_1, \dots, u_N)$ measures the influence of the *j*-th species on the growth rate of the *i*-th species. Systems of type (R) for which (A3) holds we call *competitive*.

$$\underline{a}_{i} := \inf\{f_{i}(t, x, 0, \dots, 0) : t \ge 0, x \in \overline{\Omega}\},\\ \overline{a}_{i} := \sup\{f_{i}(t, x, 0, \dots, 0) : t \ge 0, x \in \overline{\Omega}\}.$$

Note that we do not assume here that $\underline{a}_i > 0$.

(A3)
$$(\partial f_i / \partial u_j)(t, x, u) \leq 0$$
 for all $t \geq 0, x \in \overline{\Omega}, u \in [0, \infty)^N$,
 $1 \leq i, j \leq N, i \neq j$.

 $(\partial f_i/\partial u_j)(t, x, u_1, \dots, u_N)$ measures the influence of the *j*-th species on the growth rate of the *i*-th species. Systems of type (R) for which (A3) holds we call *competitive*.

(A4) There exist
$$\underline{b}_{ii} > 0$$
 such that $(\partial f_i / \partial u_i)(t, x, u) \leq -\underline{b}_{ii}$ for all $t \geq 0, x \in \overline{\Omega}, u \in [0, \infty)^N$, $1 \leq i \leq N$.

Fix a positive solution $u(t,x) = (u_1(t,x), \ldots, u_N(t,x))$ of system (R). For each $1 \le i \le N$ let $\xi_i(t), t \in [0,\infty)$, be the positive solution of the following problem

$$\begin{cases} \xi_i' = \left(\max_{x \in \bar{\Omega}} f_i(t, x, 0, \dots, 0) - \underline{b}_{ii}\xi_i\right)\xi_i,\\ \xi_i(0) = \sup_{x \in \bar{\Omega}} u_i(0, x). \end{cases}$$
(1)

Fix a positive solution $u(t,x) = (u_1(t,x), \ldots, u_N(t,x))$ of system (R). For each $1 \le i \le N$ let $\xi_i(t), t \in [0,\infty)$, be the positive solution of the following problem

$$\begin{cases} \xi_i' = \left(\max_{x \in \bar{\Omega}} f_i(t, x, 0, \dots, 0) - \underline{b}_{ii}\xi_i\right)\xi_i,\\ \xi_i(0) = \sup_{x \in \bar{\Omega}} u_i(0, x). \end{cases}$$
(1)

Lemma 1

Assume (A1) through (A4) and let $\bar{a}_i > 0$. Then for each solution $\xi_i(t)$ of the problem (1) there holds

$$\limsup_{t\to\infty}\xi_i(t)\leq \frac{\bar{\mathsf{a}}_i}{\underline{b}_{ii}},\quad 1\leq i\leq \mathsf{N}.$$

Lemma 2

Assume (A1) through (A4). Then for any positive solution $u(t,x) = (u_1(t,x), \ldots, u_N(t,x))$ of system (R), and any $1 \le i \le N$ there holds

 $u_i(t,x) \leq \xi_i(t), \qquad t \in [0, \tau_{\max}), \ x \in \overline{\Omega},$

where $\xi_i(t)$ is the solution of the problem (1).

Lemma 3 [dissipativity]

Assume (A1) through (A4) and $\bar{a}_i > 0$. Then for any maximally defined positive solution $u(t, x) = (u_1(t, x), \dots, u_N(t, x))$ of system (R) there holds (i) $\tau_{\max} = \infty$, and (ii) $\limsup_{t \to \infty} u_i(t, x) \le \frac{\bar{a}_i}{\underline{b}_{ii}}, \qquad 1 \le i \le N,$ (2) uniformly for $x \in \bar{\Omega}$.

▲ □ ▶ ▲ □ ▶ ▲ □ ▶

(A5) The derivatives $\partial f_i / \partial u_j$, $1 \le i, j \le N$, are bounded and Lipschitz continuous on sets of the form $[0, \infty) \times \overline{\Omega} \times B$, where B is a bounded subset of $[0, \infty)^N$. (A5) The derivatives $\partial f_i / \partial u_j$, $1 \le i, j \le N$, are bounded and Lipschitz continuous on sets of the form $[0, \infty) \times \overline{\Omega} \times B$, where B is a bounded subset of $[0, \infty)^N$.

Definition

For $1 \leq i, j \leq N$ and $\varepsilon_0 \geq 0$ we define

$$\overline{b}_{ij}(\varepsilon_0) := \sup \left\{ -\frac{\partial f_i}{\partial u_j}(t, x, u) : t \ge 0, \ x \in \overline{\Omega}, \\ u \in \left[0, \frac{\overline{a}_1}{\underline{b}_{11}} + \varepsilon_0\right] \times \cdots \times \left[0, \frac{\overline{a}_N}{\underline{b}_{NN}} + \varepsilon_0\right] \right\},$$

 $\overline{b}_{ij}(0) := \overline{b}_{ij}.$

(A5) The derivatives $\partial f_i / \partial u_j$, $1 \le i, j \le N$, are bounded and Lipschitz continuous on sets of the form $[0, \infty) \times \overline{\Omega} \times B$, where B is a bounded subset of $[0, \infty)^N$.

Definition

For $1 \leq i, j \leq N$ and $\varepsilon_0 \geq 0$ we define

$$\overline{b}_{ij}(\varepsilon_0) := \sup \left\{ -\frac{\partial f_i}{\partial u_j}(t, x, u) : t \ge 0, \ x \in \overline{\Omega}, \\ u \in \left[0, \frac{\overline{a}_1}{\underline{b}_{11}} + \varepsilon_0 \right] \times \cdots \times \left[0, \frac{\overline{a}_N}{\underline{b}_{NN}} + \varepsilon_0 \right] \right\},$$

 $\overline{b}_{ij}(0):=\overline{b}_{ij}.$

Assumptions (A3) and (A4) imply that $\overline{b}_{ij}(\varepsilon_0) \ge 0$, $1 \le i, j \le N$, and $\overline{b}_{ii}(\varepsilon_0) > 0$, $1 \le i \le N$, whereas it follows from (A5) that $\overline{b}_{ij}(\varepsilon_0) < \infty$, and $\lim_{\varepsilon_0 \to 0^+} \overline{b}_{ij}(\varepsilon_0) = \overline{b}_{ij}$, for $1 \le i, j \le N$.

We define the *lower average* of a function f_i as

$$m[f_i] := \liminf_{t-s\to\infty} \frac{1}{t-s} \int_s^t \min_{x\in\bar{\Omega}} f_i(\tau, x, 0, \dots, 0) d\tau,$$

Definition

We define the *upper average* of a function f_i as

$$M[f_i] := \limsup_{t-s\to\infty} \frac{1}{t-s} \int_{s}^{t} \max_{x\in\bar{\Omega}} f_i(\tau, x, 0, \dots, 0) d\tau.$$

We define the *lower average* of a function f_i as

$$m[f_i] := \liminf_{t-s\to\infty} \frac{1}{t-s} \int_s^t \min_{x\in\bar{\Omega}} f_i(\tau, x, 0, \dots, 0) d\tau,$$

Definition

We define the *upper average* of a function f_i as

$$M[f_i] := \limsup_{t-s\to\infty} \frac{1}{t-s} \int_{s}^{t} \max_{x\in\bar{\Omega}} f_i(\tau, x, 0, \dots, 0) d\tau.$$

(A6) $m[f_i] > 0, 1 \le i \le N$.

System (R) is *permanent*, if there exist positive constants δ_i and R_i such that for each positive solution $u(t, x) = (u_1(t, x), \ldots, u_N(t, x))$ of system (R) there exists T = T(u) > 0 with the property

$$\delta_i \varphi_i(x) \leq u_i(t,x) \leq R_i$$
 (permanence)

for all $1 \leq i \leq N$, $t \geq T$, $x \in \overline{\Omega}$.

System (R) is *permanent*, if there exist positive constants δ_i and R_i such that for each positive solution $u(t, x) = (u_1(t, x), \ldots, u_N(t, x))$ of system (R) there exists T = T(u) > 0 with the property

$$T_i \varphi_i(x) \le u_i(t,x) \le R_i$$
 (permanence)

for all $1 \leq i \leq N$, $t \geq T$, $x \in \overline{\Omega}$.

Average conditions for permanence in systems of PDEs

$$m[f_i] > \lambda_i \mu_i + \sum_{\substack{j=1\\j\neq i}}^{N} \frac{\overline{b}_{ij} \mathcal{M}[f_j]}{\underline{b}_{jj}}, \quad 1 \le i \le N,$$
(AC)

Assume (A1) through (A6). If (AC) holds then system (R) is permanent.

▲□ ▶ ▲ □ ▶ ▲ □ ▶

3

Assume (A1) through (A6). If (AC) holds then system (R) is permanent.

Note that in this Main Theorem we do not assume that $\underline{a}_i > 0$.

伺 ト イヨ ト イヨト

-

Assume (A1) through (A6). If (AC) holds then system (R) is permanent.

Note that in this Main Theorem we do not assume that $\underline{a}_i > 0$.

 J. Balbus and J. Mierczyński, *Time-averaging and permanence* in nonautonomous competitive systems of PDEs via Vance-Coddington estimates, Discrete and continuous dynamical systems series B, (17), 2012 p. 1407 – 1425.

一回 ト イヨト イヨト

Assume (A1) through (A6). If (AC) holds then system (R) is permanent.

Note that in this Main Theorem we do not assume that $\underline{a}_i > 0$.

 J. Balbus and J. Mierczyński, *Time-averaging and permanence* in nonautonomous competitive systems of PDEs via Vance-Coddington estimates, Discrete and continuous dynamical systems series B, (17), 2012 p. 1407 – 1425.

The following result will be useful to prove Theorem 1.

伺 ト イヨト イヨト

Theorem 2 [Vance - Coddington Estimates]

Let $c : [t_0, \infty) \to \mathbb{R}$, where $t_0 \ge 0$, be a bounded continuous function, where $c_* > 0$ and $c^* > 0$ are such that $-c_* \le c(t) \le c^*$ for all $t \ge t_0$, and let d > 0. Assume moreover that there are L > 0 and $\beta > 0$ such that

$$\frac{1}{L}\int\limits_{t}^{t+L}c(\tau)\,d\tau\geq\beta$$

for all $t \geq t_0$.

Theorem 2 [Vance - Coddington Estimates] continued

Then for any solution $\zeta(t)$ of the initial value problem

$$egin{cases} \zeta' = (c(t) - d\zeta)\zeta \ \zeta(t_0) = \zeta_0, \end{cases}$$

where $\zeta_0 > 0$, there holds

$$\frac{\beta}{d}e^{-L(c_*+\beta)} \leq \liminf_{t\to\infty} \zeta(t) \leq \limsup_{t\to\infty} \zeta(t) \leq \frac{c^*}{d}.$$
(permanence-logistic)

Theorem 2 [Vance - Coddington Estimates] continued

Then for any solution $\zeta(t)$ of the initial value problem

$$egin{cases} \zeta' = (c(t) - d\zeta)\zeta\ \zeta(t_0) = \zeta_0, \end{cases}$$

where $\zeta_0 > 0$, there holds

$$\frac{\beta}{d}e^{-L(c_*+\beta)} \leq \liminf_{t\to\infty} \zeta(t) \leq \limsup_{t\to\infty} \zeta(t) \leq \frac{c^*}{d}.$$
(permanence-logistic)

 R. R. Vance and E. A. Coddington, A nonautonomous model of population growth, J. Math. Biol. 27 (1989), no. 5, 491–506.

sketch of the proof of Theorem 1

The right-hand side of the inequality (permanence) is satisfied by Lemma 3 (ii). By assumption (A5) we can choose $\varepsilon_0 > 0$ such that

$$m[f_i] > \lambda_i \mu_i + \sum_{\substack{j=1\\j\neq i}}^{N} \frac{\overline{b}_{ij}(\varepsilon_0) M[f_j]}{\underline{b}_{jj}}$$

for all $1 \le i \le N$. Fix a positive solution $u(t, x) = (u_1(t, x), \dots, u_N(t, x))$ of system (R). Let $\xi_i(t), 1 \le i \le N, t \ge 0$, be the solutions of (1). Fix $1 \le i \le N$.

・ 同 ト ・ ヨ ト ・ ヨ ト

sketch of the proof of Theorem 1 [continued]

Let $t_0 > 0$ be such a moment that

$$u(t,x) \in \left[0, \frac{\overline{a}_1}{\underline{b}_{11}} + \varepsilon_0\right] imes \cdots imes \left[0, \frac{\overline{a}_N}{\underline{b}_{NN}} + \varepsilon_0\right]$$

for $t > t_0$ and $x \in \overline{\Omega}$. Let $\eta_i(t)$, $t \ge t_0$, be the positive solution of the following problem

$$\begin{cases} \eta_i' = \left(\min_{x \in \bar{\Omega}} f_i(t, x, 0, \dots, 0) - \lambda_i \mu_i - \overline{b}_{ii}(\varepsilon_0) \eta_i - \sum_{\substack{j=1\\j \neq i}}^N \overline{b}_{ij}(\varepsilon_0) \xi_j(t)\right) \eta_i \\ \eta_i(t_0) = \inf_{x \in \Omega} \frac{u_i(t_0, x)}{\varphi_i(x)}. \end{cases}$$
(3)
t is easy to see that $u_i(t, x) \ge \eta_i(t) \varphi_i(x)$ for all $t \ge t_0$ and $x \in \bar{\Omega}$.

→ < Ξ → <</p>

sketch of the proof of Theorem 1 [continued]

Now we apply Theorem 2 to (3) where

$$c(t) = \min_{x \in \overline{\Omega}} f_i(t, x, 0, \dots, 0) - \lambda_i \mu_i - \sum_{\substack{j=1 \\ j \neq i}}^N \overline{b}_{ij}(\varepsilon_0) \xi_j(t) \quad \text{i} \quad d = \overline{b}_{ii}(\varepsilon_0).$$

→ Ξ →

sketch of the proof Theorem 1 [continued]

To prove the permanence of system (R) we show that the parameters in Theorem 2 do not depend on the solution u(t, x), for sufficiently large t.

Now we replace conditions (AC) with

$$m[f_i] > \lambda_i \mu_i + \sum_{\substack{j=1\\j \neq i}}^{N} \frac{\overline{b}_{ij} \overline{a}_j}{\underline{b}_{jj}}$$
(4)

Then we can give the lower estimates on the numbers δ_i (in the definition of permanence) in terms of the parameters of system (R):

$$\delta_i \geq \frac{\beta}{\overline{b}_{ii}} \exp\left(-L(m[f_i] - \underline{a}_i)\right).$$
(5)

A special case of Kolmogorov systems for PDEs is a Kolmogorov systems for ODEs

$$u'_i = f_i(t, u_1, \dots, u_N)u_i \quad 1 \le i \le N. \tag{K}$$

We can treat such systems as systems of partial differential equations

$$\frac{\partial u_i}{\partial t} = \Delta u_i + f_i(t, u_1, \dots, u_N) u_i \tag{S}$$

with the Neumann boundary conditions.

Definition

System (K) is *permanent* if there exist positive constants δ_i , R_i such that for any positive solution $u(t) = (u_1(t), \ldots, u_N(t))$ of system (K) there exists T = T(u) > 0 with the property

$$\delta_i \leq u_i(t) \leq R_i$$

for $1 \leq i \leq N$, $t \geq T$.

Definition

System (K) is *permanent* if there exist positive constants δ_i , R_i such that for any positive solution $u(t) = (u_1(t), \ldots, u_N(t))$ of system (K) there exists T = T(u) > 0 with the property

$$\delta_i \leq u_i(t) \leq R_i$$

for $1 \leq i \leq N$, $t \geq T$.

Average conditions for permanence in systems of ODEs

$$m[f_i] > \sum_{\substack{j=1\\j\neq i}}^{N} \frac{\overline{b}_{ij} M[f_j]}{\underline{b}_{jj}}, \quad 1 \le i \le N,$$
(AC)_{ODE}

▲□ ▶ ▲ □ ▶ ▲ □ ▶

Assume (A1) through (A6). If $(AC)_{ODE}$ holds then system (K) is permanent.

伺 ト イヨ ト イヨト

э

Assume (A1) through (A6). If $(AC)_{ODE}$ holds then system (K) is permanent.

Theorem 3 is a special case of the Theorem 1.

→ Ξ →

Assume (A1) through (A6). If $(AC)_{ODE}$ holds then system (K) is permanent.

Theorem 3 is a special case of the Theorem 1. Note that again we do not assume that $\underline{a}_i > 0$.

Definition

System (K) is globally attractive if any two positive solutions $u(t) = (u_1(t), \dots, u_N(t))$ and $v(t) = (v_1(t), \dots, v_N(t))$ of system (R) satisfy $\lim_{t \to \infty} (u_i(t) - v_i(t)) = 0$

for $1 \leq i \leq N$.

Sufficient conditions for attractivity in systems of ODEs are not special cases of sufficient conditions for attractivity in systems of PDEs.

Lemma 4 is very technical.

Lemma 4

Assume (A1) through (A5) and (AC)_{ODE}. Let $\alpha_1, \ldots, \alpha_N > 0$ be positive constants such that for $i = 1, \ldots, N$ there holds

$$\alpha_i \underline{b}_{ii} > \sum_{\substack{j=1\\ j\neq i}}^{N} \alpha_j \overline{b}_{ji}.$$
(6)

Then there exist Z > 0 and $\gamma > 0$ such that for each pair of a positive solutions $u(t) = (u_1(t), \ldots, u_N(t))$ and $v(t) = (v_1(t), \ldots, v_N(t))$ of system (K) there exists $t_0 \ge 0$ such that

Lemma 4 [continued]

$$\sum_{i=1}^{N} |u_i(t) - v_i(t)| \le Z \sum_{i=1}^{N} |u_i(t_0) - v_i(t_0)| \cdot e^{-\gamma(t-t_0)}$$

for $t \geq t_0$.

Conditions (6) are called *column diagonal dominance*.

э

sketch of the proof

Fix a positive solutions $u(t) = (u_1(t), \ldots, u_N(t))$ and $v(t) = (v_1(t), \ldots, v_N(t))$ of system (K). We introduce a Lyapunov function

$$\Theta(t) := \sum_{i=1}^{N} \alpha_i \left| \ln \frac{u_i(t)}{v_i(t)} \right|.$$
(7)

・ 同 ト ・ ヨ ト ・ モ ト …

-

sketch of the proof continued

We prove that there exists $\varepsilon > 0$ such that

$$D^+\Theta(t) \leq -arepsilon \sum_{i=1}^N |u_i(t) - v_i(t)|$$
 dla $t \geq t_0,$ (8)

where D^+ is the upper derivative of Θ .

∃ >

sketch of the proof continued

Then using the fact that the system (K) is permanent we have that there exist $0 < \delta_* < \delta^* < \infty$ such that $\delta_* \leq u_i(t), v_i(t) < \delta^*$. By mean value theorem it follows that

$$\frac{1}{\delta^*}|u_i(t)-v_i(t)| \leq \left|\ln\frac{u_i(t)}{v_i(t)}\right| \leq \frac{1}{\delta_*}|u_i(t)-v_i(t)|. \tag{9}$$

Using (7), (8) and (9) we see that there exist $Z>0, \ \gamma>0$ such that

$$\sum_{i=1}^{N} |u_i(t) - v_i(t)| \le Z \sum_{i=1}^{N} |u_i(t_0) - v_i(t_0)| \cdot e^{-\gamma(t-t_0)}$$
(10)

Assume (A1) - (A5) and $(AC)_{ODE}$. Then system (K) is globally attractive.

Proof.

By [S. Ahmad and A. C. Lazer, Average conditions for global asymptotic stability in a nonautonomous Lotka-Volterra system, Nonlinear Anal. Ser A: Theory Methods **40** (2000), no. 1-8, 37-49, Lemma 3.2] it follows that if $(AC)_{ODE}$ holds then there exist constants $\alpha_i > 0$, i = 1, ..., N, such that

$$\alpha_i \underline{b}_{ii} > \sum_{\substack{j=1 \ j \neq i}}^{N} \alpha_j \overline{b}_{ji}$$
 for $i = 1, \dots, N$.

Now it suffices to apply Lemma 4.

A (1) > (1) > (1)

Attractivity in Kolmogorov Systems of PDEs

Now we consider system (R)

$$\begin{cases} \frac{\partial u_i}{\partial t} = \mu_i \Delta u_i + f_i(t, x, u_1, \dots, u_N) u_i, & t > 0, \ x \in \Omega, \ i = 1, \dots, N \\ \mathcal{B}_i u_i = 0, & t > 0, \ x \in \partial \Omega, \ i = 1, \dots, N, \end{cases}$$
(R)

where \mathcal{B}_i is the **Neumann** boundary conditions.

伺 ト イヨ ト イヨト

Attractivity in Kolmogorov Systems of PDEs

Now we consider system (R)

$$\begin{cases} \frac{\partial u_i}{\partial t} = \mu_i \Delta u_i + f_i(t, x, u_1, \dots, u_N) u_i, & t > 0, \ x \in \Omega, \ i = 1, \dots, N \\ \mathcal{B}_i u_i = 0, & t > 0, \ x \in \partial \Omega, \ i = 1, \dots, N \end{cases}$$
(R)

where \mathcal{B}_i is the **Neumann** boundary conditions.

Definition

System (R) is globally attractive if any two positive solutions $u(t,x) = (u_1(t,x), \dots, u_N(t,x))$ and $v(t,x) = (v_1(t,x), \dots, v_N(t,x))$ of (R) satisfy $\lim_{t \to \infty} (u_i(t,x) - v_i(t,x)) = 0$

for $1 \leq i \leq N$, uniformly in $x \in \overline{\Omega}$.

・ 同 ト ・ ヨ ト ・ ヨ ト

ъ

Again we have a very technical lemma.

Lemma 5

Assume (A1) through (A5) and (AC). Let

$$\underline{\delta}\,\underline{b}_{ii} > \sum_{\substack{j=1\\j\neq i}}^{N} \overline{\delta}\,\overline{b}_{ij}, \quad 1 \le i \le N, \tag{11}$$

where $0 < \underline{\delta} \leq \overline{\delta} < \infty$ be such that for any positive solution $u(t,x) = (u_1(t,x), \ldots, u_N(t,x))$ of system (R) there holds

$$\underline{\delta} \leq u_i(t,x) \leq \overline{\delta}$$

for sufficiently large t and all $x \in \overline{\Omega}$, $1 \le i \le N$.

Lemma 5 [continued]

Then there exist Z > 0 and $\gamma > 0$ with the property that for each pair of positive solutions $u(t, x) = (u_1(t, x), \dots, u_N(t, x))$ and $v(t, x) = (v_1(t, x), \dots, v_N(t, x))$ of system (R) there exists $t_0 \ge 0$ such that

$$\sum_{i=1}^{N} \sup_{x \in \bar{\Omega}} |u_i(t,x) - v_i(t,x)| \le Z \sum_{i=1}^{N} \sup_{x \in \bar{\Omega}} |u_i(t_0,x) - v_i(t_0,x)|$$
(12)
$$\cdot e^{(-\gamma(t-t_0))}$$

for $t \ge t_0$. In particular, system (R) is globally attractive.

・ 同 ト ・ 三 ト ・

sketch of the proof

Fix positive solutions $u(t, x) = (u_1(t, x), \ldots, u_N(t, x))$ and $v(t, x) = (v_1(t, x), \ldots, v_N(t, x))$ of system (R). A well known result from the matrix theory states that there exist $\alpha_1, \ldots, \alpha_N > 0$ such that

$$\alpha_{i}\underline{\delta}\,\underline{b}_{ii} > \sum_{\substack{j=1\\j\neq i}}^{N} \alpha_{j}\overline{\delta}\,\overline{b}_{ji}(\varepsilon), \quad 1 \le i \le N.$$
(13)

We introduce a Lyapunov functional

$$\Theta(t) = \sum_{i=1}^{N} \alpha_i \Theta_i(t), \text{ where } \Theta_i(t) := \sup_{x \in \overline{\Omega}} \left| \ln \frac{u_i(t,x)}{v_i(t,x)} \right|.$$
(14)
Fix $1 \le i \le N$.

sketch of the proof continued

We prove that

$$D^+ \Theta_i(t) \leq -\underline{\delta} \, \underline{b}_{ii} \Theta_i(t) + \overline{\delta} \sum_{\substack{j=1 \ j \neq i}}^N \overline{b}_{ij}(\varepsilon) \Theta_j(t), \qquad t \geq t_0.$$
 (15)

Note that by (13)

$$\sum_{i=1}^{N} \alpha_{i} \left(-\underline{\delta} \, \underline{b}_{ii} \Theta_{i}(t) + \overline{\delta} \sum_{\substack{j=1\\j \neq i}}^{N} \overline{b}_{ij}(\varepsilon) \Theta_{j}(t) \right) \leq -\epsilon \sum_{i=1}^{N} \Theta_{i}(t),$$
(16)

-

sketch of the proof continued

Hence by (15), (16) and the definition of Θ we have that

$$\sum_{i=1}^{N} \sup_{x \in \bar{\Omega}} |u_i(t,x) - v_i(t,x)| \le Z \sum_{i=1}^{N} \sup_{x \in \bar{\Omega}} |u_i(t_0,x) - v_i(t_0,x)|$$

$$\cdot e^{(-\gamma(t-t_0))}$$

$$\Box$$

→ < Ξ → <</p>