

PART II : GRADIENT FLOWS

- ① HILBERTIAN THEORY
- ② WEAK FORMULATIONS OF G.F. AND IMPLICIT EULER SCHEME
- ③ EXISTENCE, UNIQUENESS, STABILITY OF G.F. AND REGULARIZING EFFECTS



$$F: M \longrightarrow \mathbb{R}$$

$$\dot{x}(t) = -\nabla F(x(t)) \quad (\text{GF})$$

Ingredients:

Energy

F

metric
(distance)

$$dF_x(v) = \langle \nabla F(x), v \rangle$$

①

HILBERTIAN THEORY

$\lambda \geq 0$

We shall consider convex (or λ -convex) functions F :

$$F((1-t)x + ty) \leq (1-t)F(x) + tF(y) - \frac{\lambda}{2} t(1-t) |x-y|^2$$

$$\langle -\eta, x-y \rangle \geq \lambda |x-y|^2 \quad (\text{MONOTONICITY INEQUALITY})$$

$$\xi \in \partial F(x), \eta \in \partial F(y)$$

$$+ \frac{\lambda}{2} |y-x|^2$$

$$\partial F(x) := \{ v \mid F(y) \geq F(x) + \langle v, y-x \rangle \forall y \in H \}$$

$\nabla F(x) :=$ the element with minimal norm of $\partial F(x)$

$$D(F) := \{ F < +\infty \}$$

For convex functions in Hilbert spaces, a much more flexible formulation of (GF) is :

$$(*) \quad \begin{cases} x'(t) \in -\partial F(x(t)) & \text{a.e. } t > 0 \\ x \in AC_{loc}^2((0, +\infty); H) \\ \lim_{t \downarrow 0} x(t) = \bar{x}. \end{cases}$$

THEOREM 1. Let $F: H \rightarrow \mathbb{R} \cup \{+\infty\}$ be convex and l.s.c.

- i) (Existence and uniqueness) $\forall \bar{x} \in \overline{D(F)}$ $(*)$ has a unique solution;
- ii) (Minimal selection and energy identity) for a.e. t , $x'(t) = -\nabla F(x(t))$,
so that also the (GF) equation has a unique solution.

Moreover $F(x(t)) \in AC_{loc}((0, +\infty))$ and

$$F(x(s)) - F(x(t)) = \int_s^t |\nabla F|^2(x(r)) dr \quad \forall \quad 0 < s \leq t < \infty$$

($s=0$ if $\bar{x} \in D(F)$)

iii) (Regularizing effects) $x'_+(t) = -\nabla F(x(t))$, $(F \circ x)'_+(t) = -|\nabla F|^2(x(t))$

for all $t > 0$, and

$$F(x(t)) \leq \inf_{v \in D(F)} \left\{ F(v) + \frac{1}{2t} |v - \bar{x}|^2 \right\},$$

$$|\nabla F|^2(x(t)) \leq \inf_{v \in D(\partial F)} \left\{ |\nabla F|^2(v) + \frac{1}{t^2} |v - \bar{x}|^2 \right\}.$$

iv) (Asymptotic behaviour)

$$F(x(t)) - F(x_{\min}) \leq (F(\bar{x}) - F(x_{\min})) e^{-2\lambda t}$$

In particular, if $\lambda > 0$, the ENERGY INEQUALITY $F(x) - F(x_{\min}) \geq \frac{\lambda}{2} |x - x_{\min}|^2$ gives

$$|x(t) - x_{\min}| \leq \sqrt{\frac{2}{\lambda} (F(\bar{x}) - F(x_{\min}))} e^{-\lambda t}.$$

② WEAK FORMULATIONS OF (GF) : (EDI) and (EVI)

We encode both the system (GF) and the energy identity in a single inequality:

$$\frac{d}{dt} F(x(t)) \leq -\frac{1}{2} |\nabla F(x(t))|^2 - \frac{1}{2} |x'(t)|^2.$$

Indeed, along any curve $y(t)$, we have

$$\begin{aligned} \frac{d}{dt} F(y(t)) &= \langle \nabla F(y(t)), y'(t) \rangle \\ &\geq -|\nabla F(y(t))| |y'(t)| \quad (= \text{iff } -y'(t) \parallel \nabla F(y(t))) \\ &\geq -\frac{1}{2} |\nabla F|^2(y(t)) - \frac{1}{2} |y'(t)|^2 \\ &\quad \nearrow \\ &= \text{iff } |\nabla F(y(t))| = |y'(t)| \end{aligned}$$

It is technically more convenient to consider the inequality in an integral form, namely:

$$\frac{1}{2} \int_0^t |x'(r)|^2 dr + \frac{1}{2} \int_0^t |\nabla F(x(r))|^2 dr \leq F(\bar{x}) - F(x(t)) \quad (\text{EDI})$$

We will see that:

- 1) (EDI) makes sense also in metric spaces;
- 2) (EDI) has a discrete counterpart.

let us consider now the (EVI) formulation. This one relies

- very much on two ingredients:
- A global ENERGY INEQUALITY (and therefore convexity!)
 - The DERIVATIVE OF SQUARED DISTANCE

In Hilbert spaces both ingredients are easy: if u solves (GF) we have

$$\begin{aligned} \frac{d}{dt} \frac{1}{2} \|u(t) - v\|^2 &= \langle u'(t), u(t) - v \rangle \\ &= \langle -u'(t), v - u(t) \rangle \\ &\leq F(v) - F(u(t)) - \frac{\lambda}{2} \|v - u(t)\|^2 \end{aligned}$$

DEFINITION. In a metric space (E, d) , an absolutely continuous curve

$u(t)$ is said to be an (EVI) solution to (GF) if

$$\frac{d}{dt} \frac{1}{2} d^2(u(t), v) \leq \frac{-\lambda}{2} d^2(v, u(t)) + F(v) - F(u(t)) \quad \text{for a.e. } t > 0, \forall v \in \mathcal{D}(F) \quad (\text{EVI})$$

Under suitable assumptions on (d, F) , (EVI) has a discrete version as well.

The (EVI) formulation is very strong, and it leads easily to stability (for instance with respect to Γ -convergence of the energy F) and to contractivity.

THEOREM 2. (CONTRACTIVITY) let x, y be solutions to (EVI).

Then $d(x(t), y(t)) \leq d(\bar{x}, \bar{y}) e^{-\lambda t}$

PROOF. Insert $v = y(t)$ in

$$\frac{d}{dt} d^2(x(t), v) \leq 2F(v) - 2F(x(t)) - \lambda d^2(x(t), v)$$

and $w = x(t)$ in

$$\frac{d}{dt} d^2(y(t), w) \leq 2F(w) - 2F(y(t)) - \lambda d^2(y(t), w)$$

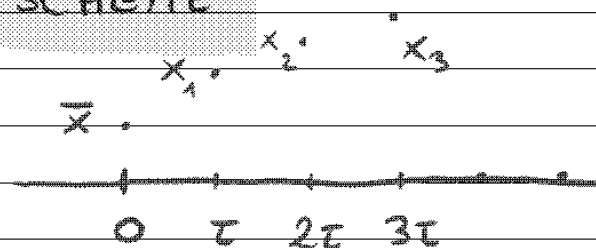
to obtain the differential inequality

$$\frac{d}{dt} d^2(x(t), y(t)) \leq -2\lambda d^2(x(t), y(t)).$$

This argument can be made rigorous using, for instance, KRUZIKHOV method of doubling of variables.

THE IMPLICIT EULER SCHEME

$\tau > 0$ time step



$$X_{\frac{t}{\tau}}(t) := x_{m+1} \quad t \in (m\tau, (m+1)\tau], \quad m \geq 0$$

$$X_0(0) = \bar{x}$$

The sequence (x_m) is built recursively: $x_0 = \bar{x}$ and

$$x_{m+1} \text{ minimizes } y \mapsto F(y) + \frac{1}{2\tau} d^2(y, x_m)$$

THE HILBERT, CONVEX CASE

The minimality of x_{k+1} gives the discrete Euler equation

$$(*) \quad \frac{x_{k+1} - x_k}{\tau} \in -\partial F(x_{k+1}),$$

so that $x_{k+1} = (\text{Id} + \tau \partial F)^{-1}(x_k)$. In terms of the piecewise
offline interpolant \tilde{x}_{τ} , (*) reads

$[\cdot] = \text{integer part}$

$$\tilde{x}_{\tau}'(t) \in -\partial F\left((\text{Id} + \tau \partial F)^{-1}(\tilde{x}_{\tau}(\tau [t/\tau]))\right).$$

This is the explicit time discretization scheme for the ODE

$$y'(t) = -(\partial F)_\tau(y(t)), \text{ where}$$

$$(\partial F)_\tau := \frac{\text{Id} - (\text{Id} + \tau \partial F)^{-1}}{\tau} = \partial F \circ (\text{Id} + \tau \partial F)^{-1}.$$

This is the (ODE) used in the classical existence proofs

by approximation: $(\partial F)_\tau \in \text{lip}(H, H)$, with $\text{lip}((\partial F)_\tau) \leq 2/\tau$.

In order to show that x_τ converges as $\tau \rightarrow 0$ to a continuous solution of (GF) we have to read (E1) and (EVI) inside the Euler scheme.

HOW (ED1) CAN BE READ IN THE EULER SCHEME

DEFINITION (SLOPE) Let $F: E \rightarrow \mathbb{R} \cup \{+\infty\}$ and $x \in D(F)$.

We set
$$|\partial F|(x) = \limsup_{y \rightarrow x} \frac{[F(x) - F(y)]^+}{d(x, y)}$$

Equivalently, $|\partial F|(x)$ is the smallest $C \geq 0$ satisfying

$$F(y) \geq F(x) - C d(x, y) + o(d(x, y)).$$

With this characterization, a simple application of Hahn-Banach theorem gives

$$|\partial F|(x) = |\nabla F|(x), \quad \text{for } E = H, F \text{ convex, l.s.c.}$$

Using the concept of slope we can give a meaning also to absolutely continuous maps $x: [0, +\infty) \rightarrow E$:

$$\frac{1}{2} \int_0^t |x'(r)|^2 dr + \frac{1}{2} \int_0^t |\partial F(x(r))|^2 dr \leq F(\bar{x}) - F(x(t)), \quad t > 0$$

metric derivative

LEMMA 3. (FIRST DISCRETE EULER EQUATION) let $y \in E$ such that

$$F(y) + \frac{1}{2\tau} d^2(y, x) = \min_v F(v) + \frac{1}{2\tau} d^2(v, x).$$

Then $|\partial F|(y) \leq d(x, y)/\tau$.

PROOF. $F(y) - F(\tilde{y}) \leq \frac{1}{2\tau} \{d^2(\tilde{y}, x) - d^2(y, x)\} \leq \frac{d(y, \tilde{y})}{2\tau} (d(y, x) + d(\tilde{y}, x))$

$$|\partial F(y)| \leq \lim_{\tilde{y} \rightarrow y} \frac{1}{2\tau} (d(\tilde{y}, x) + d(y, x)) = d(x, y)/\tau \blacksquare$$

Now we can interpolate between x and y in a VARIATIONAL way, as follows.

For $\sigma \in (0, \tau)$ we choose y_σ among the minimizers of $\tilde{y} \rightarrow F(\tilde{y}) + \frac{1}{2\sigma} d^2(\tilde{y}, x)$.

LEMMA 4. $g(\sigma) := F(y_\sigma) + \frac{1}{2\sigma} d^2(y_\sigma, x) \in \text{lip}_{\text{loc}}((0, \tau])$ and

$$g'(\sigma) = -\frac{1}{\sigma^2} d^2(y_\sigma, x)$$

Since $g(0_+) = F(x)$, by integration from 0 to τ the lemma gives

$$\begin{aligned} F(x) - F(y) &= \frac{d^2(x, y)}{2\tau} + \int_0^\tau d^2(y_\sigma, x) / 2\sigma^2 d\sigma \\ &\geq \tau \frac{d^2(x, y)}{2\tau^2} + \frac{1}{2} \int_0^\tau |\partial F|^2(y_\sigma) d\sigma \\ &\sim \frac{\tau}{2} |x'|^2 \quad \sim \tau/2 |\partial F|^2 \end{aligned}$$

Adding all inequalities with $(x, y) = (x_k, x_{k+1})$ one obtains an approximate version of (ED1) for \hat{X}_τ (the variational interpolation) that provides, in the limit as $\tau \rightarrow 0$, solutions to (ED1).

PROOF OF LEMMA 4

$$\begin{aligned} g(\sigma+h) - g(\sigma) &\leq \left\{ \left(F(y_\sigma) + \frac{1}{2(\sigma+h)} d^2(y_\sigma, x) \right) - \left(F(y_\sigma) + \frac{1}{2\sigma} d^2(y_\sigma, x) \right) \right\} \\ &= -\frac{h}{2\sigma^2} d^2(y_\sigma, x) + o(h) \end{aligned}$$

At any differentiability point σ , we get $g'(\sigma) = -\frac{1}{2\sigma^2} d^2(y_\sigma, x)$.

HOW (EVI) CAN BE READ IN THE EULER SCHEME

CONVEXITY IN LENGTH METRIC SPACES. $F: E \rightarrow \mathbb{R} \cup \{+\infty\}$

is said to be λ -convex if $t \rightarrow F(\gamma(t))$ is $\lambda d^2(x, y)$ -convex along all constant speed geodesics $\gamma: [0, 1] \rightarrow E$, $\gamma(0) = x$, $\gamma(1) = y$.

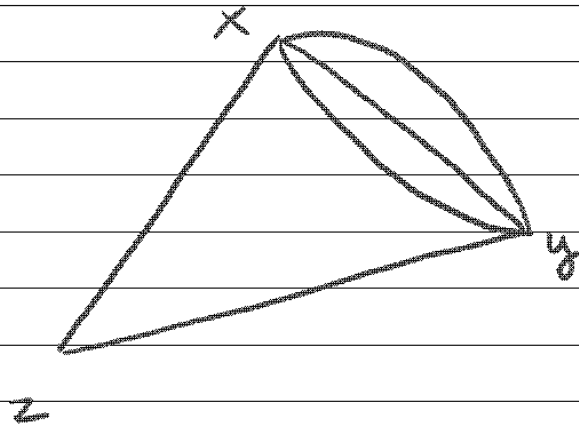
Equivalently

$$F(\gamma(t)) \leq (1-t)F(x) + tF(y) - \frac{1}{2} \lambda t(1-t) d^2(x, y)$$

NON POSITIVELY CURVED METRIC SPACES. A length space (E, d) is said to be NPC if $\frac{1}{2} d^2(\cdot, z)$ is 1-convex for all $z \in E$.

The definition, due to ALEXANDROV, is motivated by the Hilbertian identity

$$\frac{1}{2} |(1-t)x + ty - z|^2 = (1-t) \frac{1}{2} |x-z|^2 + t \frac{1}{2} |y-z|^2 - \frac{1}{2} t(1-t) |y-x|^2$$



NPC $K < 0$

PC $K > 0$

The theory of gradient flows works well for convex functionals in PC spaces. Unfortunately, we will see that $\mathcal{O}_2(H)$ is PC!

DEFINITION. We say that F and d are COMPATIBLE if $\forall x, y, z \in E$

there exists a continuous curve $\gamma: [0, 1] \rightarrow E$ with $\gamma(0) = x$, $\gamma(1) = y$

and i) $F(\gamma(t)) \leq (1-t)F(x) + tF(y) - \frac{\lambda}{2} t(1-t) d^2(x, y)$;

ii) $\frac{1}{2} d^2(\gamma(t), z) \leq (1-t) \frac{1}{2} d^2(x, z) + t \frac{1}{2} d^2(y, z) - \frac{t(1-t)}{2} d^2(x, y)$.

Of course, if E is NPC and F is λ -convex, then F and d are compatible.

LEMMA 4. (SECOND DISCRETE EULER EQUATION) If (F, d) are

compatible, and $F(y) + \frac{1}{2\tau} d^2(y, x) = \min_{z \in E} \left\{ F(z) + \frac{1}{2\tau} d^2(z, x) \right\},$

then

$$\frac{1}{2\tau} (d^2(y, z) - d^2(x, z)) \leq F(z) - F(y) \quad \forall z \in E.$$

$$\sim \frac{d}{dt} d^2(x(t), z)$$

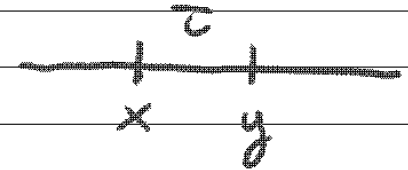
PROOF. $(\lambda=0)$ $F(y) + \frac{1}{2\tau} d^2(y, x) \leq F(y_t) + \frac{1}{2\tau} d^2(y_t, x)$ $y_0 = y$
 $y_1 = z$

$$(\text{conv. of } F \text{ and } d^2(\cdot, x)) \leq (1-t) F(y) + t F(z) + \frac{(1-t)}{2\tau} d^2(y, x) + \frac{t}{2\tau} d^2(z, x) - \frac{t(1-t)}{2\tau} d^2(y, z)$$

$$F(y) - F(z) \leq \frac{1}{2\tau} d^2(x, z) - \frac{(1-t)}{2\tau} d^2(y, z) \quad \text{let } t \downarrow 0 \quad \blacksquare$$

Now, using the discrete (EVI) property

$$\frac{1}{\tau} (d^2(y, z) - d^2(x, z)) \leq F(z) - F(y) \quad \forall z$$



we can recover precisely the Hilbertian theory.

ASSUMPTIONS

- (E, d) complete metric space;
- $F \geq 0$, l.s.c. compatible with d ;
- The discrete semigroup $S_{\tau}^{\bar{x}}(t)$ exists.

not really
necessary →

THEOREM 5 (EXISTENCE AND UNIQUENESS) For all $\bar{x} \in \overline{D(F)}$ there exists a (unique) solution $S\bar{x}(t)$ of (EVI) starting from \bar{x} . If $\bar{x} \in D(F)$ it satisfies the a priori estimate

$$\sup_{t \geq 0} d(S_{\tau}\bar{x}(t), S\bar{x}(t)) \leq 8\sqrt{\tau} \sqrt{F(\bar{x})}.$$

THEOREM 6 (REGULARIZING EFFECTS AND POINTWISE FORMULATIONS) $x(t) = S\bar{x}(t)$

1) the right metric derivative $|x'(t_+)|$ exists $\forall t > 0$ and

$$|x'(t_+)| = |\partial F|(x(t));$$

2) $t \rightarrow F(x(t))$ is locally AC in $(0, +\infty)$, right differentiable

and
$$\frac{d}{dt_+} F(x(t)) = -|\partial F|^2(x(t));$$

$$3) \quad F(x(t)) \leq \inf_v \left\{ F(v) + \frac{1}{2t} d^2(v, \bar{x}) \right\}$$

$$|\partial F|^2(x(t)) \leq \inf_v \left\{ |\partial F|^2(v) + \frac{1}{t^2} d^2(v, \bar{x}) \right\}.$$

let us prove convergence of S_τ and the quasi error estimates when $\bar{x} \in D(F)$.

Strategy: Compare S_τ to $S_{\tau/2}$, using $(EVI)_\tau$.

LEMMA 7. For $t = n\tau$, $n \geq 1$, we have

$$d^2\left(S_{\frac{\tau}{2}} \bar{x}(t), S_{\frac{\tau}{2}} \bar{y}(t)\right) - d^2(\bar{x}, \bar{y}) \leq 2\tau F(\bar{x})$$

PROOF (Step 1) We show the inequality for $t = \tau$, precisely

$$d^2(S_{\tau}\bar{x}(\tau), S_{\tau/2}\bar{y}(\tau)) - d^2(\bar{x}, \bar{y}) \leq 2\tau \{ F(\bar{x}) - F(S_{\tau}\bar{x}(\tau)) \} \quad (1)$$

By (EVI) $_{\tau/2}$ we get

$$d^2(S_{\tau/2}\bar{y}(\tau/2), z) - d^2(\bar{y}, z) \leq \tau \{ F(z) - F(S_{\tau/2}\bar{y}(\tau/2)) \} \quad (2)$$

+

$$d^2(S_{\tau/2}\bar{y}(\tau), z) - d^2(S_{\tau/2}\bar{y}(\tau/2), z) \leq \tau \{ F(z) - F(S_{\tau/2}\bar{y}(\tau)) \} \quad (3)$$

$$d^2(S_{\tau/2}\bar{y}(\tau), z) - d^2(\bar{y}, z) \leq 2\tau \{ F(z) - F(S_{\tau/2}\bar{y}(\tau)) \} \quad (4)$$

$$d^2(S_{\tau}\bar{x}(\tau), z) - d^2(\bar{x}, z) \leq 2\tau \{ F(z) - F(S_{\tau}\bar{x}(\tau)) \} \quad (5)$$

Now, let $z = \bar{x}$ in (4) and $z = S_{\frac{\tau}{2}} \bar{y}(\tau)$ in (5) and add, to get

$$d^2(S_{\frac{\tau}{2}} \bar{x}(\tau), S_{\frac{\tau}{2}} \bar{y}(\tau)) - d^2(\bar{x}, \bar{y}) \leq 2\tau \{ F(\bar{x}) - F(S_{\frac{\tau}{2}} \bar{x}(\tau)) \}. \quad (6)$$

Step 2 From (6) we get

$$d^2(S_{\frac{\tau}{2}} \bar{x}(2\tau), S_{\frac{\tau}{2}} \bar{y}(2\tau)) - d^2(S_{\frac{\tau}{2}} \bar{x}(\tau), S_{\frac{\tau}{2}} \bar{y}(\tau)) \leq 2\tau \{ F(S_{\frac{\tau}{2}} \bar{x}(\tau)) - F(S_{\frac{\tau}{2}} \bar{x}(2\tau)) \}$$

Add, to get

$$d^2(S_{\frac{\tau}{2}} \bar{x}(2\tau), S_{\frac{\tau}{2}} \bar{y}(2\tau)) - d^2(\bar{x}, \bar{y}) \leq 2\tau \{ F(\bar{x}) - F(S_{\frac{\tau}{2}} \bar{x}(2\tau)) \}.$$

..... 

The lemma with $\bar{x} = \bar{y}$ gives

$$d\left(S_{\tau/2^i} \bar{x}(t), S_{\tau/2^{i+1}} \bar{x}(t)\right) \leq 2^{(1-i)/2} \sqrt{\tau} \sqrt{F(\bar{x})}$$

Therefore $S_{\tau/2^i} \longrightarrow S^\tau$ as $i \rightarrow \infty$, with

$$d\left(S_{\tau} \bar{x}(t), S^\tau(t)\right) \leq \sum_{i=0}^{\infty} 2^{(1-i)/2} \sqrt{\tau} \sqrt{F(\bar{x})}.$$

We conclude showing that S^τ solves (EVI):

Indeed, we can read $(EVI)_\tau$ in the sense of distributions as

$$\frac{d}{dt} \frac{1}{2} d^2 \left(S_{\frac{\tau}{2}} \bar{x}(t), z \right) \leq \sum_{n=0}^{\infty} \tau \left(F(z) - F \left(S_{\frac{\tau}{2}} \bar{x}((n+1)\tau) \right) \right) \delta_{n\tau}$$

\parallel
 $\tau \lceil t/\tau \rceil + \tau$

Since $\limsup_{\tau \downarrow 0} -F \left(S_{\frac{\tau}{2}} \bar{x}(\tau + \tau \lceil t/\tau \rceil) \right) \leq -F \left(S_{\frac{\tau}{2}}^{\tau} \bar{x}(t) \right)$

we get

$$\frac{d}{dt} \frac{1}{2} d^2 \left(S_{\frac{\tau}{2}}^{\tau} \bar{x}(t), z \right) \leq \left(F(z) - F \left(S_{\frac{\tau}{2}}^{\tau} \bar{x}(t) \right) \right) 2^{\frac{1}{2}}.$$

Proof of regularizing effects.

Integrate from 0 to t (EVI) and use monotonicity of $t \rightarrow F(x(t))$ to get

$$\begin{aligned} \frac{1}{2} (d^2(x(t), v) - d^2(\bar{x}, v)) &\leq \int_0^t F(v) - F(x(s)) \, ds \\ &\leq t (F(v) - F(x(t))), \quad \text{i.e.} \end{aligned}$$

$$F(x(t)) \leq F(v) + \frac{1}{2t} d^2(v, \bar{x})$$

To prove the regularization of $|\partial F|(x(t))$ we use the slope estimate

$$\frac{F(u) - F(v)}{d(u, v)} \leq |\partial F(u)|$$

and

$$\lim_{t \rightarrow 0} t F(x(t)) = 0 :$$

$$\begin{aligned} \frac{t^2}{2} |\partial F|^2(x(t)) &\leq \int_0^t \lambda |\partial F|^2(x(s)) ds \\ &= - \int_0^t \lambda (F(x(s)))' ds \end{aligned}$$

$$= \int_0^t F(x(s)) ds - t F(x(t))$$

$$(EVI) \quad \leq t F(v) + \frac{1}{2} (d^2(\bar{x}, v) - d^2(x(t), v)) - t F(x(t))$$

$$\leq t |\partial F(v)| d(v, x(t)) + \frac{1}{2} d^2(\bar{x}, v) - \frac{1}{2} d^2(x(t), v)$$

$$\leq \frac{t^2}{2} |\partial F(v)|^2 + \frac{1}{2} d^2(\bar{x}, v)$$

$$|\partial F|^2(x(t)) \leq |\partial F(v)|^2 + \frac{1}{t^2} d^2(v, \bar{x}).$$

STABILITY OF (EVI) :

- 1) With respect to \bar{x} ;
- 2) With respect to F

(SEQUENTIAL) Γ -CONVERGENCE $F_h, F: X \rightarrow \overline{\mathbb{R}}$
 (X, σ)

$$\Gamma(\sigma)\text{-}\limsup_{h \rightarrow \infty} F_h(x) = \inf \left\{ \limsup_{h \rightarrow \infty} F_h(x_h) \mid x_h \xrightarrow{\sigma} x \right\}$$

$$\Gamma(\sigma)\text{-}\liminf_{h \rightarrow \infty} F_h(x) = \inf \left\{ \liminf_{h \rightarrow \infty} F_h(x_h) \mid x_h \xrightarrow{\sigma} x \right\}$$

$F = \Gamma(\sigma)\text{-}\lim_{h \rightarrow \infty} F_h$ if the two Γ -limits are equal, i.e.

$$\Gamma\text{-}\liminf_{h \rightarrow \infty} F_h \geq F \geq \Gamma\text{-}\limsup_{h \rightarrow \infty} F_h$$

Equivalently

$$\forall x_h \xrightarrow{\sigma} x \quad \liminf_{h \rightarrow \infty} F_h(x_h) \geq F(x) \quad (1)$$

$$\forall \varepsilon > 0 \exists x_h \xrightarrow{\sigma} x \quad \limsup_{h \rightarrow \infty} F_h(x_h) \leq F(x) + \varepsilon. \quad (2)$$

It is often useful to consider topologies in (1) and (2), with the first weaker than the second.

THEOREM 8 (STABILITY) (E, d) metric, $F_n, F : E \rightarrow \overline{\mathbb{R}}$.

- 1) (F_n, d) , $n \in \mathbb{N}$ and (F, d) are compatible;
- 2) $\Gamma(d) - \limsup_{n \rightarrow \infty} F_n \leq F$;
- 3) $\Gamma(\sigma) - \liminf_{n \rightarrow \infty} F_n \geq F$ for some topology σ for which d is sequentially lower semicontinuous
- 4) F_n are equi-coercive in bounded sets of E for the topology σ .

Then, if $\bar{x}_n \in D(F_n)$ satisfy $d(\bar{x}_n, \bar{x}) \rightarrow 0$, $F_n(\bar{x}_n) \rightarrow F(\bar{x}) \in \mathbb{R}$, the corresponding (EVI) solutions converge locally uniformly in $[0, +\infty)$.

SKETCH OF PROOF By the universal error estimate

$$d(S\bar{x}(t), S_{\tau}\bar{x}(t)) \leq 8 \sqrt{\tau F(\bar{x})}$$

we need only to show pointwise convergence of the discrete semigroups, i.e.

$$x_h \rightarrow x, \quad y_h \text{ minimizes } z \rightarrow F_h(z) + \frac{1}{2\tau} d^2(z, x_h)$$

$$\Rightarrow y_h \rightarrow y, \quad \text{where } y \text{ minimizes}$$

$$z \rightarrow F(z) + \frac{1}{2\tau} d^2(z, x)$$

The assumptions we made on F_h imply, whenever $x_h \rightarrow x$,

$$\Gamma(\sigma) - \lim_{h \rightarrow \infty} F_h(\cdot) + \frac{1}{2\tau} d^2(\cdot, x_h) = F(\cdot) + \frac{1}{2\tau} d^2(\cdot, x)$$

and therefore convergence of minimizers to minimizers.

[illegible]