
Complete surfaces with negative extrinsic curvature

in $\mathbb{M}^2 \times \mathbb{R}$

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Abstract

We prove that there exist no complete vertical graphs in $\mathbb{M}^2 \times \mathbb{R}$ with extrinsic curvature bounded from above by a negative constant, when \mathbb{M}^2 is a Riemannian surface with a pole and non negative curvature.

1 Introduction.

In 1964, Efimov proved that no complete surface can be \mathcal{C}^2 -immersed in the Euclidean 3-space \mathbb{R}^3 if its extrinsic curvature K_{ext} is bounded from above by a negative constant (see [3], [8]). This generalized Hilbert's classical result which stated that no complete smooth immersion exists with negative constant extrinsic curvature in \mathbb{R}^3 .

Efimov's theorem has been tried to extend in several ways (see [4], [10], [9]). In this sense, not much is known about the behaviour of the extrinsic curvature of a complete surface in product spaces $\mathbb{M}^2 \times \mathbb{R}$ (see [1], [5]).

In this paper we prove that there exist no entire vertical graphs with extrinsic curvature bounded from above by a negative constant in $\mathbb{M}^2 \times \mathbb{R}$, where \mathbb{M}^2 is a Riemannian surface with a pole and with non negative curvature $K_{\mathbb{M}}$. In our arguments we use Heinz's ideas, who showed this result when \mathbb{R}^3 is the ambient space (see [7]).

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As a consequence of a result in [6] we obtain that, if \mathbb{M}^2 is a Riemannian surface with $K_{\mathbb{M}} \geq 0$ and with a pole, then every entire vertical graph Σ in $\mathbb{M}^2 \times \mathbb{R}$ satisfies

$$\inf_{\Sigma} |K_{ext}| = 0,$$

where K_{ext} denotes the extrinsic curvature of Σ .

Moreover, we construct examples of the existence of complete surfaces with constant negative extrinsic curvature in certain product spaces $\mathbb{M}^2 \times \mathbb{R}$.

2 Graphs with negative extrinsic curvature.

Let \mathbb{M}^2 be a Riemannian surface and (r, θ) local geodesic polar coordinates around a point $p_0 \in \mathbb{M}^2$ which are well defined for $r < R$, for a certain $R > 0$. The induced metric is given by

$$\langle \cdot, \cdot \rangle = dr^2 + G(r, \theta)d\theta^2.$$

We consider $\mathbb{M}^2 \times \mathbb{R}$ endowed with the product metric and a vertical graph Σ in $\mathbb{M}^2 \times \mathbb{R}$ over the geodesic disk $B(p_0, R)$ centered at p_0 and with radius R , given in local coordinates as

$$\psi(r, \theta) = \left(\exp_{p_0}(r \cos(\theta), r \sin(\theta)), z(r, \theta) \right),$$

which we identify with $(r, \theta, z(r, \theta))$ in order to simplify notation.

We denote by $\{\partial_r, \partial_\theta\}$ and $\{\bar{\partial}_r, \bar{\partial}_\theta\}$ the partial derivatives with respect to r and θ on \mathbb{M}^2 and Σ respectively, where, for instance, $\partial_r \equiv \frac{\partial}{\partial r}$ and $\partial_\theta \equiv \frac{\partial}{\partial \theta}$. Then

$$\begin{aligned} \bar{\partial}_r &= \partial_r + z_r \partial_t \\ \bar{\partial}_\theta &= \partial_\theta + z_\theta \partial_t. \end{aligned}$$

Thus, the induced metric on Σ is given by

$$ds^2 = (1 + z_r^2) dr^2 + 2z_r z_\theta dr d\theta + (G + z_\theta^2) d\theta^2$$

and its second fundamental form is given by

$$\begin{aligned} \langle \nabla_{\bar{\partial}_r} \bar{\partial}_r, N \rangle &= \frac{z_{rr}}{\sqrt{1 + z_r^2 + \frac{z_\theta^2}{G}}} \\ \langle \nabla_{\bar{\partial}_\theta} \bar{\partial}_r, N \rangle &= \frac{1}{\sqrt{1 + z_r^2 + \frac{z_\theta^2}{G}}} \left(-\frac{z_\theta G_r}{2G} + z_{r\theta} \right) \\ \langle \nabla_{\bar{\partial}_\theta} \bar{\partial}_\theta, N \rangle &= \frac{1}{\sqrt{1 + z_r^2 + \frac{z_\theta^2}{G}}} \left(\frac{z_r G_r}{2} - \frac{z_\theta G_\theta}{2} + z_{\theta\theta} \right), \end{aligned}$$

where ∇ is the Levi-Civita connection on $\mathbb{M}^2 \times \mathbb{R}$ and

$$N = \frac{-1}{\sqrt{1 + z_r^2 + \frac{z_\theta^2}{G}}} \left(z_r \partial_r + \frac{z_\theta}{G} \partial_\theta - \partial_t \right)$$

is the pointing upwards unit normal vector of the graph.

By using the above formulae, a straightforward computation gives

$$\begin{aligned} & \left(\sqrt{G} \right)_r d \left(\left(z_r^2 + \frac{z_\theta^2}{G} \right) d\theta \right) + d \left(z_r d \left(\frac{z_\theta}{\sqrt{G}} \right) - \frac{z_\theta}{\sqrt{G}} dz_r \right) \\ &= 2\sqrt{G} \left(1 + z_r^2 + \frac{z_\theta^2}{G} \right)^2 K_{ext} (dr \wedge d\theta), \end{aligned} \quad (1)$$

where K_{ext} denotes the extrinsic curvature of Σ .

Now we define the following auxiliary function which will be useful for our purposes

$$f(r) = \int_{B_r} \sqrt{G} \left(1 + \frac{z_\theta^2}{G} \right), \quad r > 0$$

where B_r denotes the ball centered at the origin of \mathbb{R}^2 and radius r , with $r < R$. Here, we are identifying \mathbb{R}^2 and the tangent plane of \mathbb{M}^2 at p_0 , $T_{p_0}\mathbb{M}^2$, in the usual way.

We observe that along this section we will work with functions of type $\int_{B_r} h(\rho, \theta)$, where $h(\rho, \theta)$ is well defined in $B_r \setminus \{(0, 0)\}$. However all these functions $h(\rho, \theta)$ can be continuously extended to the origin as it happens for the previous $f(r)$. This is due to the facts that $\lim_{p \rightarrow p_0} \sqrt{G}(p) = 0$, $\lim_{p \rightarrow p_0} \left(\sqrt{G} \right)_\rho(p) = 1$ (see [2]) and the functions $\left| \frac{z_\theta}{\sqrt{G}} \right|$ and $|z_\rho|$ are bounded in a neighbourhood of the origin.

Lemma 1. *Under these conditions, we have*

$$|B_r| \leq f(r) \leq \sqrt{|B_r|} \left(\int_{B_r} \sqrt{G} \left(1 + z_\rho^2 + \frac{z_\theta^2}{G} \right)^2 \right)^{\frac{1}{2}}.$$

where $|B_r|$ denotes the area of the geodesic disk $B(p_0, r)$ in \mathbb{M}^2 .

Proof. Since $\frac{z_\theta^2}{G} \geq 0$, the first inequality is clear. Moreover, by using the Cauchy-Schwarz inequality, one has

$$f(r) \leq \left(\int_{B_r} \sqrt{G} \right)^{\frac{1}{2}} \left(\int_{B_r} \sqrt{G} \left(1 + z_\rho^2 + \frac{z_\theta^2}{G} \right)^2 \right)^{\frac{1}{2}} = \sqrt{|B_r|} \left(\int_{B_r} \sqrt{G} \left(1 + z_\rho^2 + \frac{z_\theta^2}{G} \right)^2 \right)^{\frac{1}{2}}.$$

□

Lemma 2. *Let us denote by $K_{\mathbb{M}}$ the Gauss curvature of \mathbb{M}^2 . Then in the previous conditions we have,*

$$\begin{aligned} \frac{d}{dr} \int_0^{2\pi} \left(\frac{z_\theta^2}{\sqrt{G}} \right) d\theta &= \int_0^{2\pi} (\sqrt{G})_r z_r^2 d\theta + \int_{B_r} \left(z_\rho^2 + \frac{z_\theta^2}{G} \right) K_{\mathbb{M}} \sqrt{G} \\ &\quad - 2 \int_{B_r} \sqrt{G} \left(1 + z_\rho^2 + \frac{z_\theta^2}{G} \right)^2 K_{ext}. \end{aligned}$$

Proof. From (1) we can write

$$\begin{aligned} &2 \int_{B_r} \sqrt{G} \left(1 + z_\rho^2 + \frac{z_\theta^2}{G} \right)^2 K_{ext} \\ &= \int_{B_r} \left[(\sqrt{G})_\rho d \left(\left(z_\rho^2 + \frac{z_\theta^2}{G} \right) d\theta \right) + d \left(z_\rho d \left(\frac{z_\theta}{\sqrt{G}} \right) - \frac{z_\theta}{\sqrt{G}} dz_\rho \right) \right] \\ &= \int_{B_r} \left((\sqrt{G})_\rho - 1 \right) d \left(\left(z_\rho^2 + \frac{z_\theta^2}{G} \right) d\theta \right) \\ &\quad + \int_{B_r} \left[d \left(\left(z_\rho^2 + \frac{z_\theta^2}{G} \right) d\theta \right) + d \left(z_\rho d \left(\frac{z_\theta}{\sqrt{G}} \right) - \frac{z_\theta}{\sqrt{G}} dz_\rho \right) \right]. \end{aligned} \quad (2)$$

Using the Green theorem and integrating by parts one gets

$$\begin{aligned} &\int_{B_r} \left((\sqrt{G})_\rho - 1 \right) d \left(\left(z_\rho^2 + \frac{z_\theta^2}{G} \right) d\theta \right) \\ &= \int_{B_r} d \left(\left((\sqrt{G})_\rho - 1 \right) \left(z_\rho^2 + \frac{z_\theta^2}{G} \right) d\theta \right) - \int_{B_r} \left(z_\rho^2 + \frac{z_\theta^2}{G} \right) d \left(\left((\sqrt{G})_\rho - 1 \right) d\theta \right) \\ &= \int_0^{2\pi} \left((\sqrt{G})_r - 1 \right) \left(z_r^2 + \frac{z_\theta^2}{G} \right) d\theta - \int_{B_r} \left(z_\rho^2 + \frac{z_\theta^2}{G} \right) \left((\sqrt{G})_{\rho\rho} \right) \\ &= \int_0^{2\pi} (\sqrt{G})_r z_r^2 d\theta - \int_0^{2\pi} z_r^2 d\theta + \int_0^{2\pi} \left((\sqrt{G})_r - 1 \right) \frac{z_\theta^2}{G} d\theta \\ &\quad + \int_{B_r} \left(z_r^2 + \frac{z_\theta^2}{G} \right) K_{\mathbb{M}} \sqrt{G}, \end{aligned} \quad (3)$$

where we have used that $K_{\mathbb{M}} = \frac{-(\sqrt{G})_{rr}}{\sqrt{G}}$.

On the other hand, using again the Green theorem one obtains

$$\begin{aligned} &\int_{B_r} \left[d \left(\left(z_\rho^2 + \frac{z_\theta^2}{G} \right) d\theta \right) + d \left(z_\rho d \left(\frac{z_\theta}{\sqrt{G}} \right) - \frac{z_\theta}{\sqrt{G}} dz_\rho \right) \right] \\ &= \int_0^{2\pi} z_r^2 + \frac{z_\theta^2}{G} d\theta + \int_0^{2\pi} z_r d \left(\frac{z_\theta}{\sqrt{G}} \right) - \frac{z_\theta}{\sqrt{G}} dz_r d\theta \\ &= \int_0^{2\pi} z_r^2 + \frac{z_\theta^2}{G} + \frac{z_r z_{\theta\theta}}{\sqrt{G}} - \frac{z_r z_\theta G_\theta}{2G\sqrt{G}} - \frac{z_\theta z_{r\theta}}{\sqrt{G}} d\theta. \end{aligned} \quad (4)$$

We observe that

$$\int_0^{2\pi} \frac{z_r z_{\theta\theta}}{\sqrt{G}} - \frac{z_r z_{\theta} G_{\theta}}{2G\sqrt{G}} + \frac{z_{\theta} z_{r\theta}}{\sqrt{G}} d\theta = \int_0^{2\pi} \frac{\partial}{\partial \theta} \left(\frac{z_r z_{\theta}}{\sqrt{G}} \right) d\theta = 0. \quad (5)$$

Moreover, it is easy to check

$$2 \int_0^{2\pi} \frac{z_{\theta} z_{r\theta}}{\sqrt{G}} d\theta = \frac{d}{dr} \int_0^{2\pi} \frac{z_{\theta}^2}{\sqrt{G}} d\theta + \int_0^{2\pi} \left(\sqrt{G} \right)_r \frac{z_{\theta}^2}{G} d\theta. \quad (6)$$

Using formulae (4)-(6) we have

$$\begin{aligned} & \int_{B_r} \left[d \left(\left(z_{\rho}^2 + \frac{z_{\theta}^2}{G} \right) d\theta \right) + d \left(z_{\rho} d \left(\frac{z_{\theta}}{\sqrt{G}} \right) - \frac{z_{\theta}}{\sqrt{G}} dz_{\rho} \right) \right] \\ &= \int_0^{2\pi} z_r^2 d\theta + \int_0^{2\pi} \left(1 - \left(\sqrt{G} \right)_r \right) \frac{z_{\theta}^2}{G} d\theta - \frac{d}{dr} \int_0^{2\pi} \frac{z_{\theta}^2}{\sqrt{G}} d\theta. \end{aligned} \quad (7)$$

Finally, by adding (3) and (7), we obtain (2). \square

Recall that a point p_0 in a manifold \mathbb{M}^2 is said to be a pole if the exponential map is a diffeomorphism from the tangent plane at p_0 onto \mathbb{M}^2 . In such a case, \mathbb{M}^2 is complete.

Remark 2.1. Let \mathbb{M}^2 be a Riemannian surface as above with a pole at p_0 . Let us observe that, in these conditions, $\left(\sqrt{G} \right)_r$ is a non-negative function if the Gauss curvature $K_{\mathbb{M}}$ of \mathbb{M}^2 is non negative. Since

$$\left(\sqrt{G} \right)_{rr} = -K_{\mathbb{M}} \sqrt{G} \leq 0,$$

one has that \sqrt{G} is concave as a function of r . Fixed an arbitrary θ_0 , if there existed a point $r_0 > 0$ such that $\left(\sqrt{G} \right)_r (r_0, \theta_0) < 0$ then, from the concavity of $\sqrt{G}(\cdot, \theta_0)$ we would have that $\sqrt{G}(r, \theta_0) = 0$ for a certain $r > r_0$.

Now, we can establish the main Theorem of this section.

Theorem 1. Let \mathbb{M}^2 be a Riemannian surface with a pole. If the Gaussian curvature of \mathbb{M}^2 is non negative then there is no entire vertical graph Σ in $\mathbb{M}^2 \times \mathbb{R}$ with extrinsic curvature bounded from above by a negative constant.

Proof. Differentiating f twice and using Lemma 2 one has

$$\begin{aligned} f''(r) &= \frac{d}{dr} \int_0^{2\pi} \sqrt{G} \left(1 + \frac{z_{\theta}^2}{G} \right) d\theta = \int_0^{2\pi} \left(\sqrt{G} \right)_r d\theta + \frac{d}{dr} \int_0^{2\pi} \frac{z_{\theta}^2}{\sqrt{G}} d\theta \\ &= \int_0^{2\pi} \left(\sqrt{G} \right)_r \left(1 + z_r^2 \right) d\theta + \int_{B_r} \left(z_{\rho}^2 + \frac{z_{\theta}^2}{G} \right) K_{\mathbb{M}} \sqrt{G} \\ &\quad - 2 \int_{B_r} \sqrt{G} \left(1 + z_{\rho}^2 + \frac{z_{\theta}^2}{G} \right)^2 K_{ext}. \end{aligned}$$

Since $K_{\mathbb{M}} \geq 0$, it is clear from Remark 2.1 that the following inequality holds

$$\int_0^{2\pi} \left(\sqrt{G}\right)_r (1 + z_r^2) d\theta + \int_{B_r} \left(z_\rho^2 + \frac{z_\theta^2}{G}\right) K_{\mathbb{M}} \sqrt{G} \geq 0.$$

Thus, using that $K_{ext} \leq -\alpha$ for a certain positive constant α

$$f''(r) \geq -2 \int_{B_r} \sqrt{G} \left(1 + z_\rho^2 + \frac{z_\theta^2}{G}\right)^2 K_{ext} \geq 2\alpha \int_{B_r} \sqrt{G} \left(1 + z_\rho^2 + \frac{z_\theta^2}{G}\right)^2 \geq \frac{2\alpha}{|B_r|} f(r)^2$$

by Lemma 1.

From the last inequality

$$\frac{d}{d\rho} (f'(\rho)^2) = 2f'(\rho)f''(\rho) \geq 2f'(\rho) \frac{2\alpha}{|B_\rho|} f(\rho)^2 \geq f'(\rho) \frac{4\alpha}{|B_r|} f(\rho)^2 = \frac{4\alpha}{3|B_r|} \frac{d}{d\rho} (f(\rho)^3).$$

By integrating both sides of the above inequality one gets

$$\int_\epsilon^r \frac{d}{d\rho} (f'(\rho)^2) \geq \int_\epsilon^r \frac{4\alpha}{3|B_r|} \frac{d}{d\rho} (f(\rho)^3),$$

where $0 < \epsilon < r$. Thus,

$$f'(r)^2 \geq \frac{4\alpha}{3|B_r|} (f(r)^3 - f(\epsilon)^3) + f'(\epsilon)^2 \geq \frac{4\alpha}{3|B_r|} (f(r)^3 - f(\epsilon)^3).$$

It is clear from the definition of f that $f(\epsilon) \rightarrow 0$ when $\epsilon \rightarrow 0$, hence

$$f'(r)^2 \geq \frac{4\alpha}{3|B_r|} f(r)^3$$

and so

$$-\frac{d}{dr} \left(f(r)^{-\frac{1}{2}}\right) = \frac{1}{2} f(r)^{-\frac{3}{2}} f'(r) \geq \frac{1}{2} f(r)^{-\frac{3}{2}} \sqrt{\frac{4\alpha}{3|B_r|}} f(r)^{\frac{3}{2}} = \sqrt{\frac{\alpha}{3|B_r|}}.$$

Let R_1 and R_2 be real numbers such that $0 < R_1 < R_2$. By integrating we have on one hand

$$\int_{R_1}^{R_2} -\frac{d}{dr} \left(f(r)^{-\frac{1}{2}}\right) dr = -f(R_2)^{-\frac{1}{2}} + f(R_1)^{-\frac{1}{2}}.$$

On the other hand, since $K_{\mathbb{M}} \geq 0$, from the volume comparison theorem we have $|B_r| \leq \pi r^2$, and one has from the above inequality

$$\begin{aligned} \int_{R_1}^{R_2} -\frac{d}{dr} \left(f(r)^{-\frac{1}{2}}\right) dr &\geq \int_{R_1}^{R_2} \sqrt{\frac{\alpha}{3|B_r|}} dr = \sqrt{\frac{\alpha}{3}} \int_{R_1}^{R_2} \frac{1}{\sqrt{|B_r|}} dr \\ &\geq \sqrt{\frac{\alpha}{3}} \int_{R_1}^{R_2} \frac{1}{r\sqrt{\pi}} dr = \sqrt{\frac{\alpha}{3\pi}} \log\left(\frac{R_2}{R_1}\right). \end{aligned}$$

So, by Lemma 1

$$|B_{R_1}|^{-\frac{1}{2}} \geq f(R_1)^{-\frac{1}{2}} \geq f(R_1)^{-\frac{1}{2}} - f(R_2)^{-\frac{1}{2}} \geq \sqrt{\frac{\alpha}{3\pi}} \log\left(\frac{R_2}{R_1}\right).$$

Hence

$$\sqrt{\frac{3\pi}{\alpha}} |B_{R_1}|^{-\frac{1}{2}} \geq \log\left(\frac{R_2}{R_1}\right),$$

that is,

$$R_2 \leq R_1 \exp\left(\sqrt{\frac{3\pi}{\alpha}} \frac{1}{\sqrt{|B_{R_1}|}}\right)$$

for every $0 < R_1 < R_2$, with R_2 an arbitrary real value. \square

We observe that if \mathbb{M}^2 is compact then, for any entire vertical graph Σ in $\mathbb{M}^2 \times \mathbb{R}$ there exist points in Σ with non negative extrinsic curvature. This happens at the points where the height function achieves a local maximum or a local minimum.

Finally, as a consequence of Theorem 1 and [6, Theorem 1] we have

Corollary 1. *Let \mathbb{M}^2 be a Riemannian surface with a pole and non negative Gauss curvature. If Σ is an entire vertical graph in $\mathbb{M}^2 \times \mathbb{R}$ with extrinsic curvature K_{ext} then*

$$\inf_{\Sigma} |K_{ext}| = 0.$$

3 Complete surfaces with constant negative extrinsic curvature.

In this section we will give an example of existence of complete surfaces with strictly negative extrinsic curvature in product manifolds.

Consider \mathbb{M}^2 as the surface \mathbb{R}^2 with the induced metric

$$\langle \cdot, \cdot \rangle = d\rho^2 + G(\rho)d\theta^2$$

which is well defined in $\mathbb{R}^2 \setminus \{(0, 0)\}$, where (ρ, θ) are the usual polar coordinates of \mathbb{R}^2 . Here, the function $G(\rho)$ will be defined later.

Let Σ be a rotation surface in $\mathbb{M}^2 \times \mathbb{R}$ parametrized by

$$\Psi(r, \theta) = \left(k(r) \cos(\theta), k(r) \sin(\theta), z(r)\right) \equiv \left(k(r), \theta, z(r)\right)$$

where $k(r) > 0$ and $z(r)$ are smooth functions, and r denotes the arc length parameter of the curve $\beta(r) = \Psi(r, 0)$. Thus

$$k'(r)^2 + z'(r)^2 = 1. \tag{8}$$

If we denote by $\{\overline{\partial}_r, \overline{\partial}_\theta\}$ and $\{\partial_\rho, \partial_\theta\}$ the respective partial derivatives of Σ and \mathbb{M}^2 we have

$$\begin{aligned}\overline{\partial}_r(r, \theta) &= k'(r)\partial_\rho(k(r), \theta) + z'(r)\partial_t(k(r), \theta) \\ \overline{\partial}_\theta(r, \theta) &= \partial_\theta(k(r), \theta).\end{aligned}$$

So from (8), the induced metric in our surface is given by

$$ds^2 = dr^2 + G(k(r))d\theta^2,$$

and its second fundamental form is

$$II(r, \theta) = \left(-k''(r)z'(r) + k'(r)z''(r) \right) dr^2 + \left(\frac{z'(r)G_\rho(k(r))}{2} \right) d\theta^2.$$

Hence, the principal curvatures of Σ can be written as

$$\begin{aligned}\lambda_1 &= -k''(r)z'(r) + k'(r)z''(r) \\ \lambda_2 &= z'(r)\frac{G_\rho(k(r))}{2G(k(r))},\end{aligned}$$

and the extrinsic curvature of the graph is

$$K_{ext} = -z'(r)\frac{G_\rho(k(r))}{2G(k(r))}(k''(r)z'(r) - k'(r)z''(r)). \quad (9)$$

By differentiating (8) we have

$$k'(r)k''(r) + z'(r)z''(r) = 0,$$

and so (9) becomes the following ODE for k

$$k''(r) = -\frac{2G(k(r))}{G_\rho(k(r))}K_{ext}. \quad (10)$$

Now we take, for instance, the function $G(\rho) = \rho^4 e^{\rho^4}$ and impose that the extrinsic curvature of Σ is constant -1 .

Under these conditions, (10) becomes

$$k''(r) = \frac{k(r)}{2(1 + k(r)^4)} \quad (11)$$

Now, let $k(r)$ be a solution of the previous ODE with initial conditions $k(0) = k_0 > 0$, $k'(0) = 0$, where k_0 is a positive value which will be determined later.

It is well known that the solution $k(r)$ to the previous problem is uniquely determined in a neighbourhood of the origin. Let us see in fact that $k(r)$ is well defined for every $r \in \mathbb{R}$.

First, we observe that, from the uniqueness to the previous problem, $k(r) = k(-r)$ since $k(-r)$ is also a solution to (11) satisfying the same initial conditions. Thus, in order to study the behaviour of $k(r)$, we will only work for $r \geq 0$.

From (11) we have

$$\frac{d}{dr} (k'(r))^2 = \frac{d}{dr} \left(\frac{1}{2} \arctan (k(r)^2) \right)$$

and so

$$k'(r)^2 = c_0 + \frac{1}{2} \arctan (k(r)^2). \quad (12)$$

Hence there exists a constant c_1 such that $|k'(r)| \leq c_1$, that is $k(r)$ is globally defined as we required.

Since $k(0) = k_0 > 0$ and $k'(0) = 0$, if we take $k_0 > 0$ small enough we would have $c_0 \in \left(\frac{\pi}{4} - 1, 0\right)$. Thus, from (12) one gets $|k'(r)| < 1$ for every $r \in \mathbb{R}$. Therefore, from (8), $z(r)$ is a well defined smooth function in \mathbb{R} .

Let us see that $k(r) \geq k(0) = k_0 > 0$ for every $r \in \mathbb{R}$. In such a case, Σ is a regular surface due to the generatrix curve $\beta(r) = \Psi(r, 0)$ does not touch the rotation axis. For that purpose, let us first observe that $k(r) > 0$, for every $r > 0$.

Let us assume that there exists a first point $\epsilon > 0$ such that $k(\epsilon) = 0$. Since $k(r)$ is a positive function in the interval $[0, \epsilon)$, from (11) we obtain that $k(r)$ is a convex function in that interval. Moreover, $k'(0) = 0$, thus $k(\epsilon) \geq k(0) = k_0 > 0$, and it is contradiction with $k(\epsilon) = 0$.

On the other hand, since from (11) the function $k(r)$ is a global convex function in \mathbb{R} and $k'(0) = 0$, then $k(r) \geq k(0) = k_0$ for every $r \in \mathbb{R}$ and

$$\lim_{r \rightarrow \pm\infty} k(r) = +\infty.$$

In particular, this shows that Σ is properly immersed in $\mathbb{M}^2 \times \mathbb{R}$.

One can easily check that our metric $\langle \cdot, \cdot \rangle$ is not well defined at the origin. Since $k(r) \geq k_0 > 0$ for every $r \in \mathbb{R}$, we can perturb the metric $\langle \cdot, \cdot \rangle$ for instance for $0 \leq \rho < \frac{k_0}{2}$, and have a complete metric in \mathbb{M}^2 well defined at the origin and such that Σ preserves the same induced metric. As Σ is properly immersed in $\mathbb{M}^2 \times \mathbb{R}$, then Σ is a complete surface with negative constant extrinsic curvature as we claimed.

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